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## Convolution integral

- For CT case.
- Recall DT case:

$$x[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n - k]$$

Note: Weighed SUM of time-shifted impulses. Similarly,

$$x(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t - \tau) d\tau$$

Note: Weighted superposition of time-shifted impulses.

$$x(t) \xrightarrow{\mathcal{H}} y(t)$$

## Convolution integral (cont.)

$$y(t) = \mathcal{H} \left\{ \int_{-\infty}^{\infty} x(\tau) \delta(t - \tau) d\tau \right\} \quad \text{linear operators}$$
$$= \int_{-\infty}^{\infty} x(\tau) \mathcal{H} \{ \delta(t - \tau) \} d\tau$$

$$\delta(t - \tau) \xrightarrow{\mathcal{H}} h(t - \tau)$$

Thus,

$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau) h(t - \tau) d\tau$$

Note:

$$x(t) * h(t) = h(t) * x(t)$$

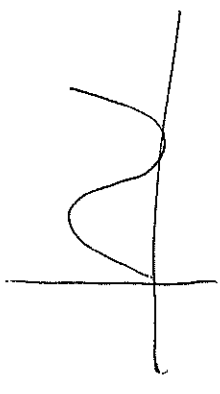
$$\delta(t) * h(t) = h(t)$$

$$\delta(t - t_0) * h(t) = h(t - t_0)$$

## Convolution Integral

E: RADAR range measurement: RADAR-Radio Detection And Ranging:

$$\text{Tx: } x(t) = \begin{cases} \sin(\omega_c t), & 0 \leq t \leq T_0 \\ 0, & \text{o.w.} \end{cases}$$



Typically,

$$h(t) = \alpha \delta(t - \beta), \quad \beta > 0$$

$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau) h(t - \tau) d\tau$$

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t - \tau) d\tau = \int_{-\infty}^{\infty} x(\tau) \propto \delta(t - \tau) d\tau$$

$$y(t) = \begin{cases} \alpha \sin(\omega_c(t - \beta)) & 0 \leq t - \beta \leq T_0 \\ 0 & \text{o.w.} \end{cases}$$

(Property of  $\delta(t)$ )

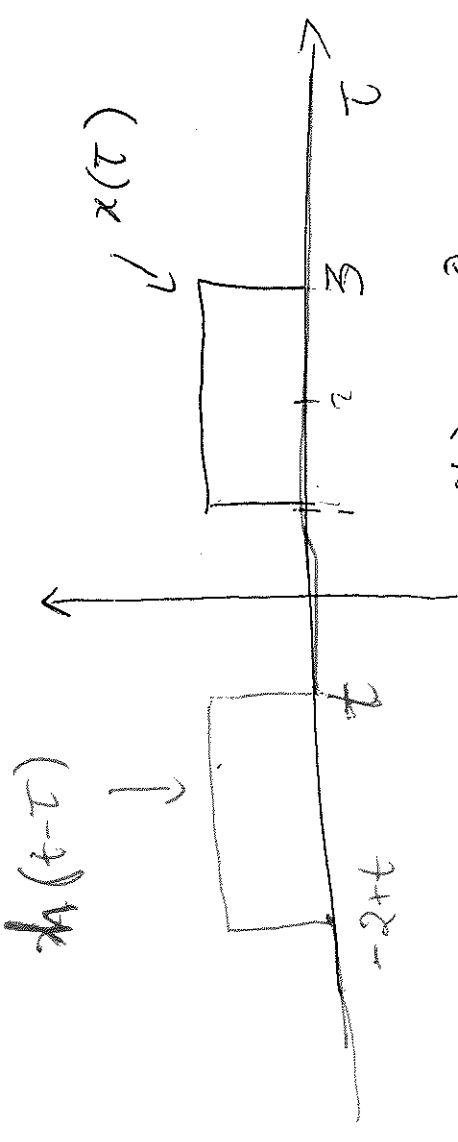
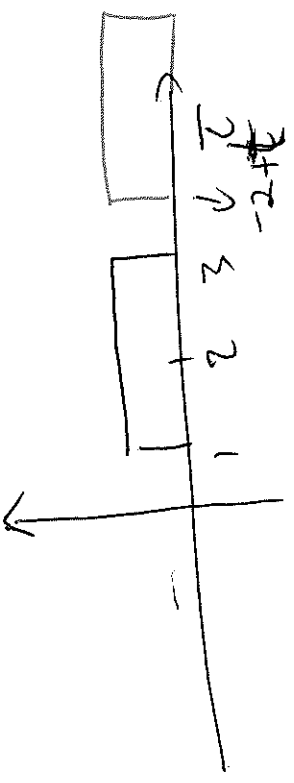
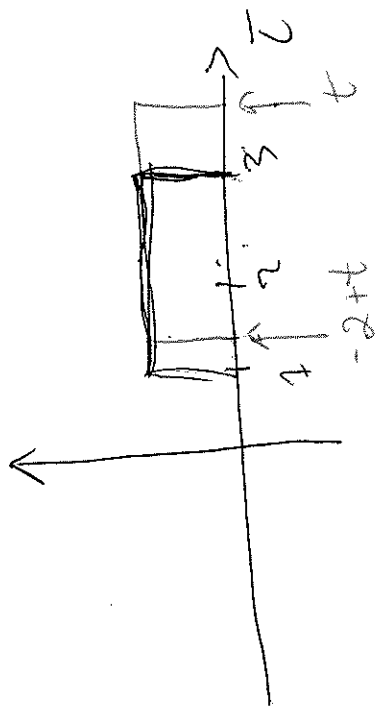
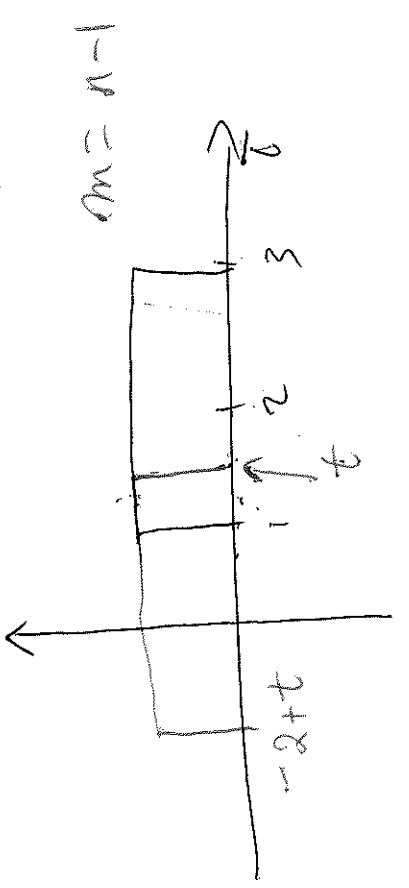
## Convolution integral evaluation procedure

1. Graph  $x(\tau)$  and  $h(\tau)$
2. Time reverse  $h(\tau) \Rightarrow h(-\tau)$
3. Time shift  $h(-\tau)$  by  $t \Rightarrow h(t - \tau)$
4. For a specific value of  $t$ , form product  $x(\tau)h(t - \tau)$
5. Integrate  $x(\tau)h(t - \tau) \Rightarrow$

$$y(t) = \int_{-\infty}^{\infty} x(\tau)h(t - \tau)d\tau$$

Q  $[1-u]s$

$u = m$   
 $[u]s = [m]s$



case 1:  $t < 1 \Rightarrow y(t) = 0$

case 2:  $y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$

$1 \leq t \leq 3$   
 $y(t) = \int_1^t (1)(1) d\tau = t-1$

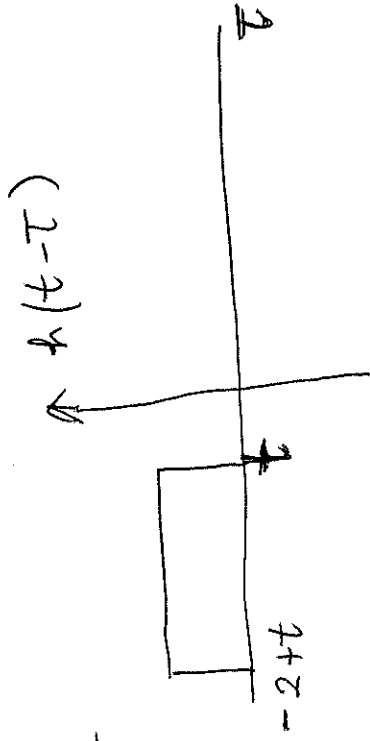
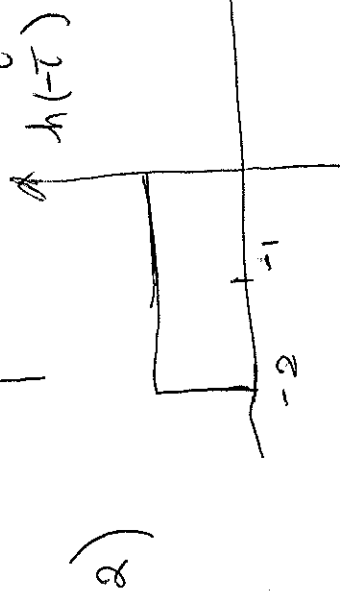
case 3:  $1 \leq -2+t \leq 3 \Rightarrow 3 \leq t \leq 5$   
 $y(t) = \int_3^t (1)(1) d\tau = 5-t$

case 4:  $3 \leq -2+t \Rightarrow t \geq 5$   
 $y(t) = 0$

# Convolution integral evaluation procedure (cont.)

Example:

$$x(t) = u(t-1) - u(t-3) \quad h(t) = u(t) - u(t-2) \quad y(t) = ??$$



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