

Convolution sum

$$x(t) = \delta(t) \xrightarrow{\mathcal{H}} y(t) = h(t)$$

$$x[n] = \delta[n] \xrightarrow{\mathcal{H}} y[n] = h[n]$$

where $h(t)$ (CT) and $h[n]$ (DT) are the system impulse responses.

$h(t)$ or $h[n]$ completely characterizes an LTI system. ■

By knowing $h(t)$ or $h[n]$, system output can be obtained for an arbitrary input signal $x(t)$ or $x[n]$. ■

How is $y(t)/y[n]$ related to $x(t)/x[n]$ and $h(t)/h[n]$?

Convolution sum (cont.)

(2)

We will start with DT systems, and then analyze CT systems.

- Any signal $x[n]$ can be expressed as a sum of time-shifted impulses as (shown graphically next slide)

$$x[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n-k]$$

$$\delta[n] \xrightarrow{H} h[n]$$

$$x[k] \delta[n] \xrightarrow{H} x[k] h[n] \quad (\text{linear property})$$

$$x[k] \delta[n-k] \xrightarrow{H} x[k] h[n-k] \quad (\text{time invariant})$$

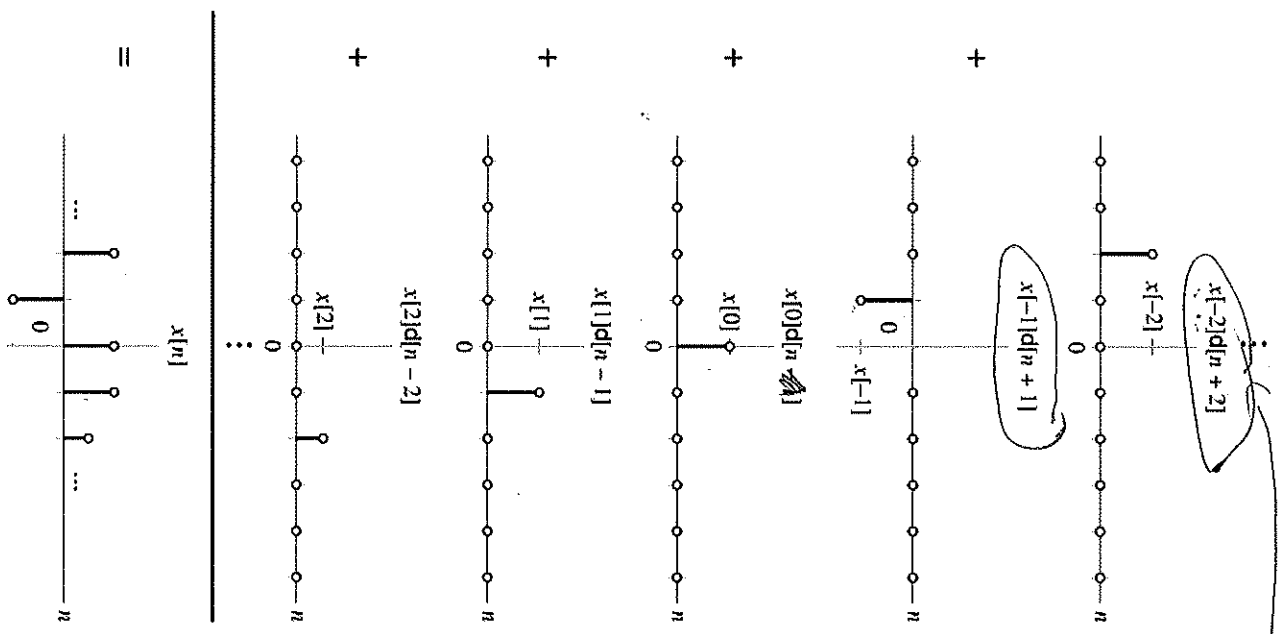
$$x[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n-k] \xrightarrow{H} \sum_{k=-\infty}^{\infty} x[k] h[n-k] =: y[n] \quad (\text{linear property})$$

Derivate:

$$\underbrace{x[n]}_{\text{convolution}} * h[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$

Convolution sum (cont.)

$$d[n+2] = \delta[n+2]$$



Convolution sum (cont.)

- Convolution sum: $x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$

- Properties of convolution as all the usual properties such as associativity, commutativity and distributivity hold

$$\begin{aligned}
 x[n] * h[n] &= h[n] * x[n] && \rightarrow \text{show this yourself.} \\
 \delta[n] * h[n] &= h[n] && \rightarrow \text{show this yourself.} \\
 \delta[n-k] * h[n] &= h[n-k] && \rightarrow \text{prove this yourself.}
 \end{aligned}$$

E: A system with input-output relationship as

$$y[n] = x[n] + (1/2)x[n-1]$$

a) System impulse response?

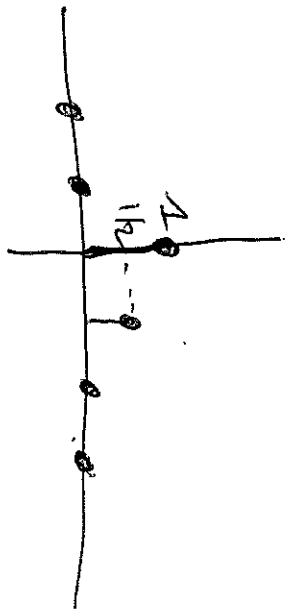
b) Find $y[n]$ for

$$x[n] = \begin{cases} 2, & n=0 \\ 4, & n=1 \\ -2, & n=2 \\ 0, & \text{o.w.} \end{cases}$$

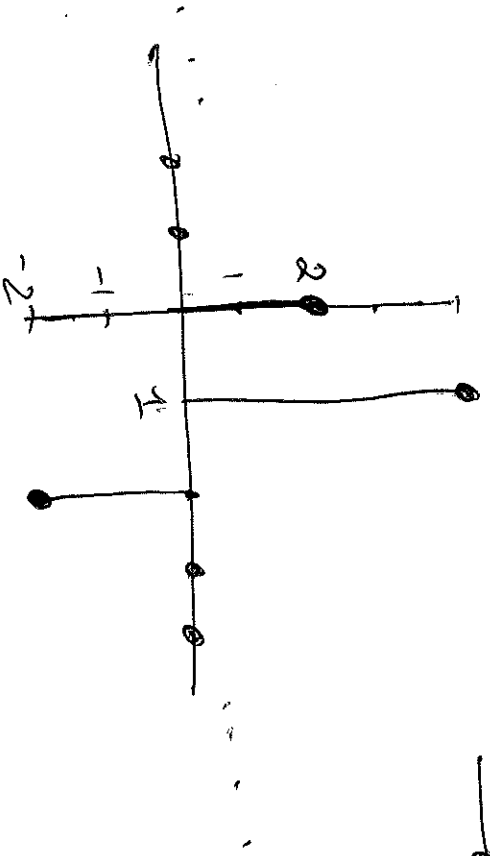
Convolution sum (cont.)

a) replacing $x[n]$ with $\delta[n]$

$$h[n] = \delta[n] + \frac{1}{2} \delta[n-1]$$



b) $x[n]$



$$x[n] = 2\delta[n] + 4\delta[n-1] - 2\delta[n-2]$$

$$y[n] = x[n] * h[n] = (2\delta[n] + 4\delta[n-1] - 2\delta[n-2]) * (\delta[n] + \frac{1}{2}\delta[n-1])$$

$$= 2\delta[n] * \delta[n] + 2\delta[n] * \frac{1}{2}\delta[n-1] + 4\delta[n-1] * \delta[n] + 4\delta[n-1] * \frac{1}{2}\delta[n-1] - 2\delta[n-2] * \delta[n] - 2\delta[n-2] * \frac{1}{2}\delta[n-1]$$

$$= 2\delta[n] + \delta[n-1] + 4\delta[n-1] + 2\delta[n-2] - 2\delta[n-2] - \delta[n-3]$$

$$= 2\delta[n] + 5\delta[n-1] - \delta[n-3]$$

Convolution sum evaluation procedure

Let $w_n[k] = x[k]h[n - k]$. Then $y[n]$ is expressed as

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} w_n[k]$$

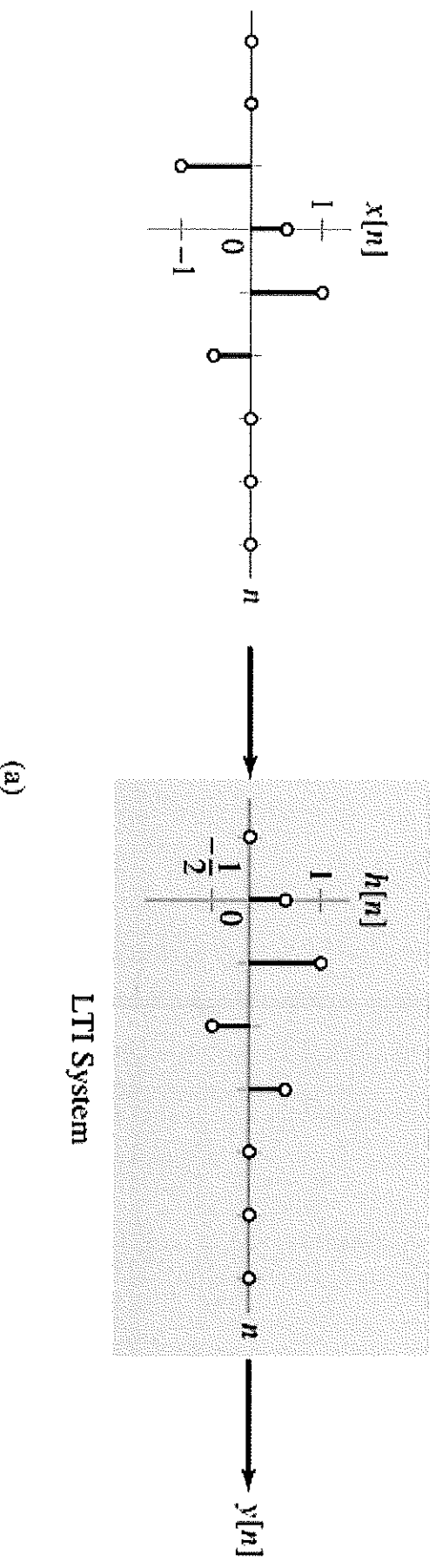
1. Graph both $x[k]$ and $h[k]$
2. Time reversal $h[k] \longrightarrow h[-k]$
3. Time shift $h[-k]$ by n shifts $\longrightarrow h[n - k]$ (left shift)
4. For a specific n , form product $x[k]h[n - k]$
5. Sum all samples of $x[k]h[n - k] \longrightarrow$

$$y[n] = \sum_{k=-\infty}^{\infty} x[k]h[n - k]$$

Convolution sum evaluation procedure (cont.)

(7)

Graphical illustration of the convolution sum: (a) LTI system with impulse response $h[n]$ and input $x[n]$.

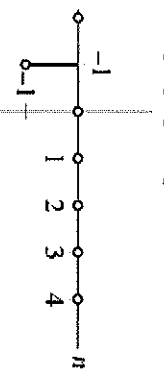


The decomposition of the input $x[n]$ into a weighted sum of time-shifted impulses results in an output $y[n]$ given by a weighted sum of time-shifted impulse responses next slide.

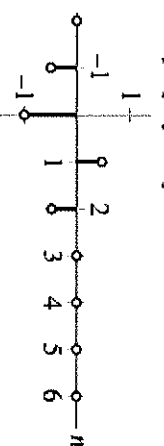
Convolution sum evaluation procedure (cont.)

8

$$k = -1 \quad x[-1] d[n+1] \quad \vdots$$

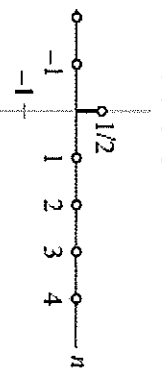


→ $h[n]$
LTI

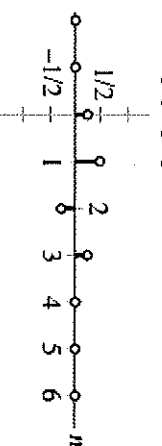


$$x[-1] h[n+1] \quad \vdots \quad k = -1$$

$$k = 0 \quad x[0] d[n]$$

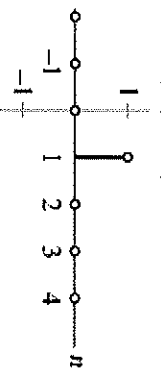


→ $h[n]$
LTI

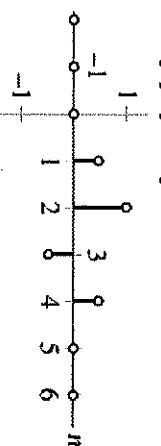


$$x[0] h[n] \quad k = 0$$

$$k = 1 \quad x[1] d[n-1]$$

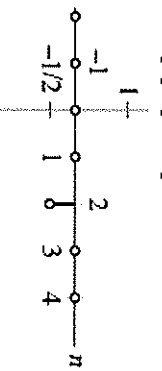


→ $h[n]$
LTI

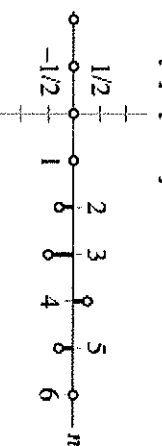


$$x[1] h[n-1] \quad k = 1$$

$$k = 2 \quad x[2] d[n-2]$$



→ $h[n]$
LTI

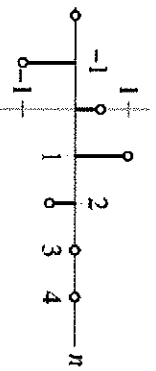


$$x[2] h[n-2] \quad k = 2$$

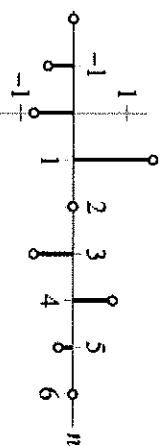
$$x[n] = \sum_{k=-\infty}^{\infty} x[k] d[n-k]$$



$$y[n] = \sum_{k=-\infty}^{\infty} x[k] h[n-k]$$



→ $h[n]$
LTI



Convolution sum evaluation procedure (cont.)

E: $x[n] = \delta[n] + \delta[n - 1] + \delta[n - 2]$ is applied to an LTI system with impulse response

$$h[n] = 4\delta[n] + 3\delta[n - 1] + 2\delta[n - 2] + \delta[n - 3]. \text{ Find } y[n].$$

$$y[n] = x[n] * h[n]$$

Exercise:

- Verify this the results using Matlab.

$$x = [1 \ 1 \ 1];$$

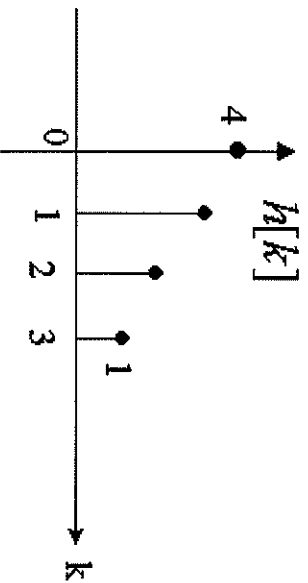
$$h = [4 \ 3 \ 2 \ 1];$$

$$y = \text{conv}(x, h);$$

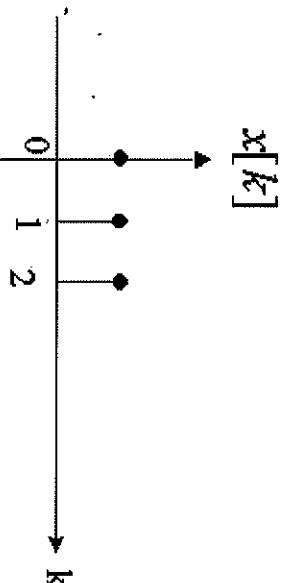
Convolution sum evaluation procedure (cont.)

27

1)

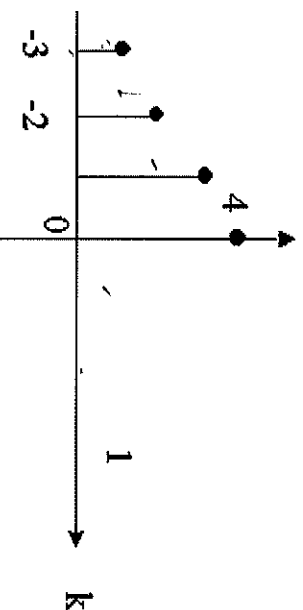


• Graph $x[k]$ & $h[k]$



2) $h[-k]$

• Form $h[-k]$ & time shift $h[-k]$



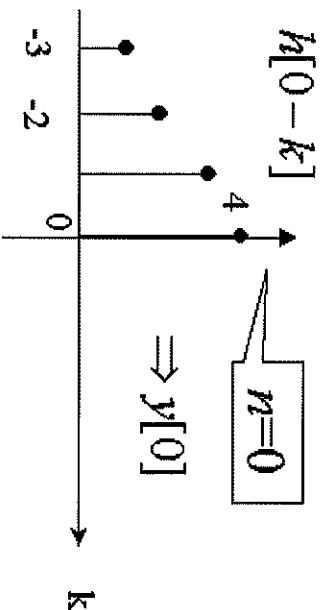
• For a specific n , form product

$$x[k]h[n-k] \Rightarrow \dots 0 \quad 0 \quad 0 \quad 0 \quad 4 \quad 0 \dots \Rightarrow y[0] = \sum = 4$$

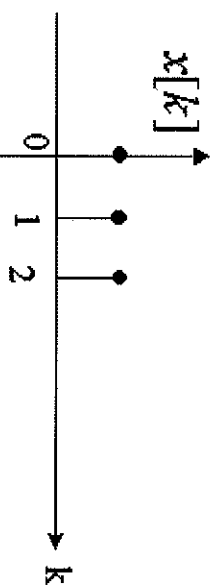
3) $h[n-k]$

$$\sum_{k=-\infty}^{\infty} x[k]h[n-k] = 0 \quad \text{for } n < 0$$

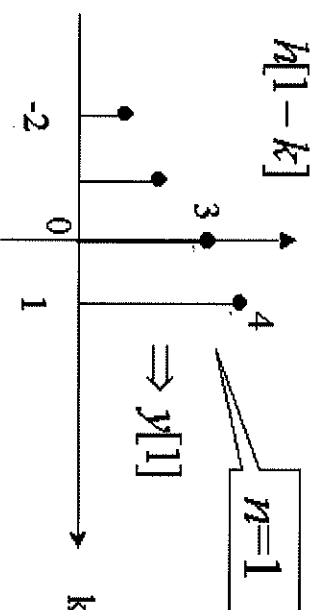
• Sum all products of $x[k]h[n-k]$



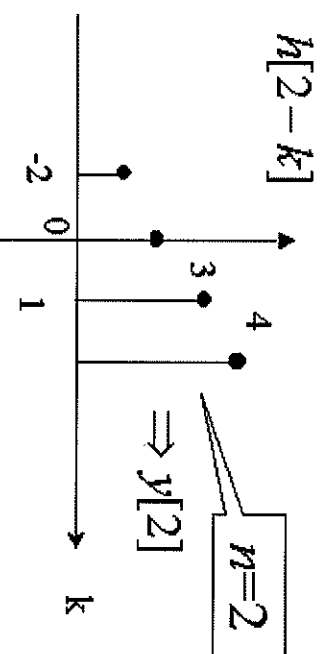
Convolution sum evaluation procedure (cont.)



$$x[k]h[n-k] \Rightarrow \dots 0 \quad 0 \quad 0 \quad 3 \quad 4 \quad 4 \quad 0 \quad 0 \quad 0 \dots \Rightarrow y[1] = \sum = 7$$



$$x[k]h[n-k] \Rightarrow \dots 0 \quad 0 \quad 0 \quad 0 \quad 2 \quad 3 \quad 3 \quad 4 \quad 4 \quad 0 \quad \dots \Rightarrow y[2] = \sum = 9$$



$$\begin{aligned}
 y[4] &= 3 \\
 y[5] &= 1 \\
 y[n] &= 0 \text{ for } n \geq 6 \\
 \dots 0 \quad 0 \quad 0 \quad 1 \quad 2 \quad 3 \quad 0 \dots \Rightarrow y[3] &= \sum = 6
 \end{aligned}$$

$y[n]$ = write in the form of $\delta[n]$ yourself.