

# Dynamic Programming 101

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$$f(n) = f(n-1) + f(n-2)$$

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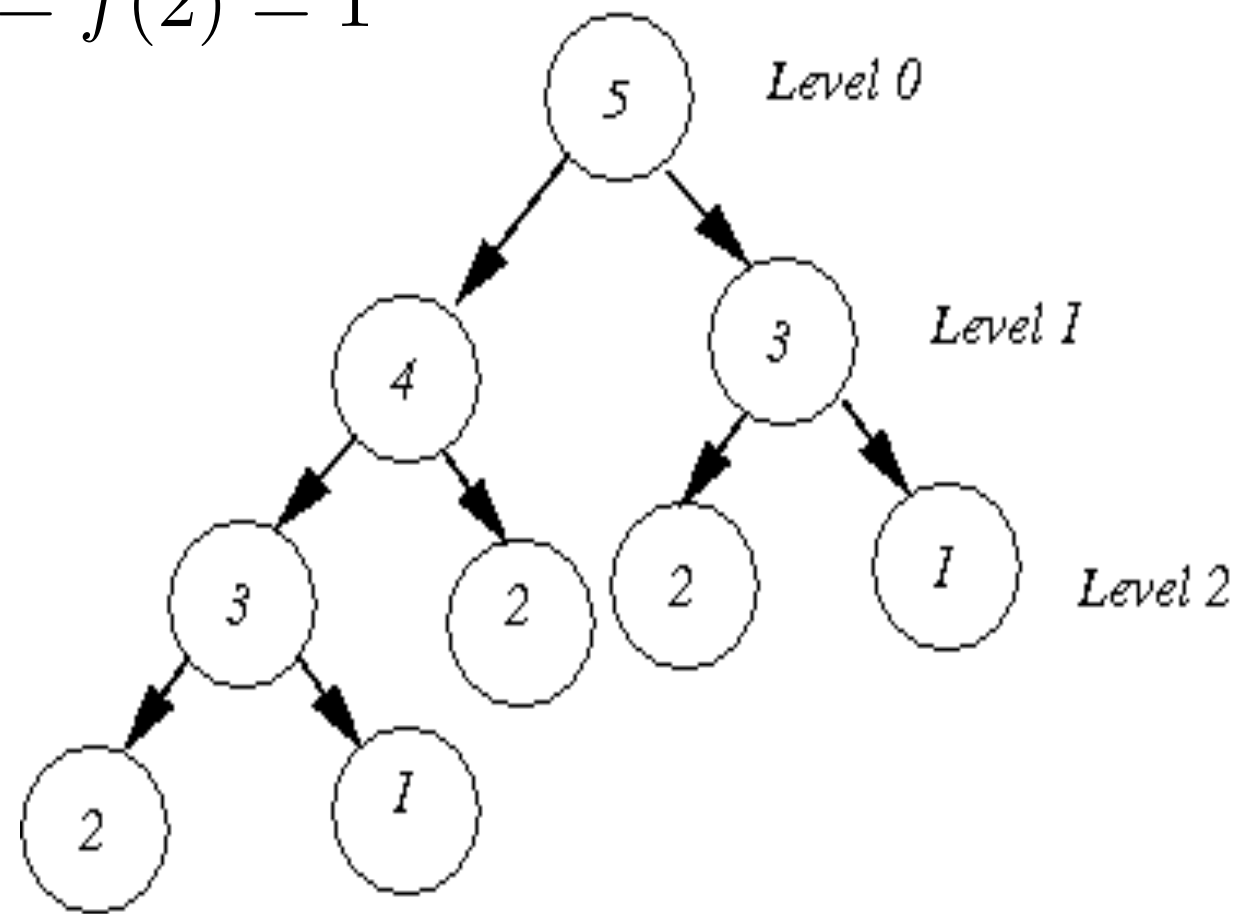
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def fib(n):  
    if n <= 2:  
        return 1  
    return fib(n-1) + fib(n-2)
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# Dynamic Programming I01

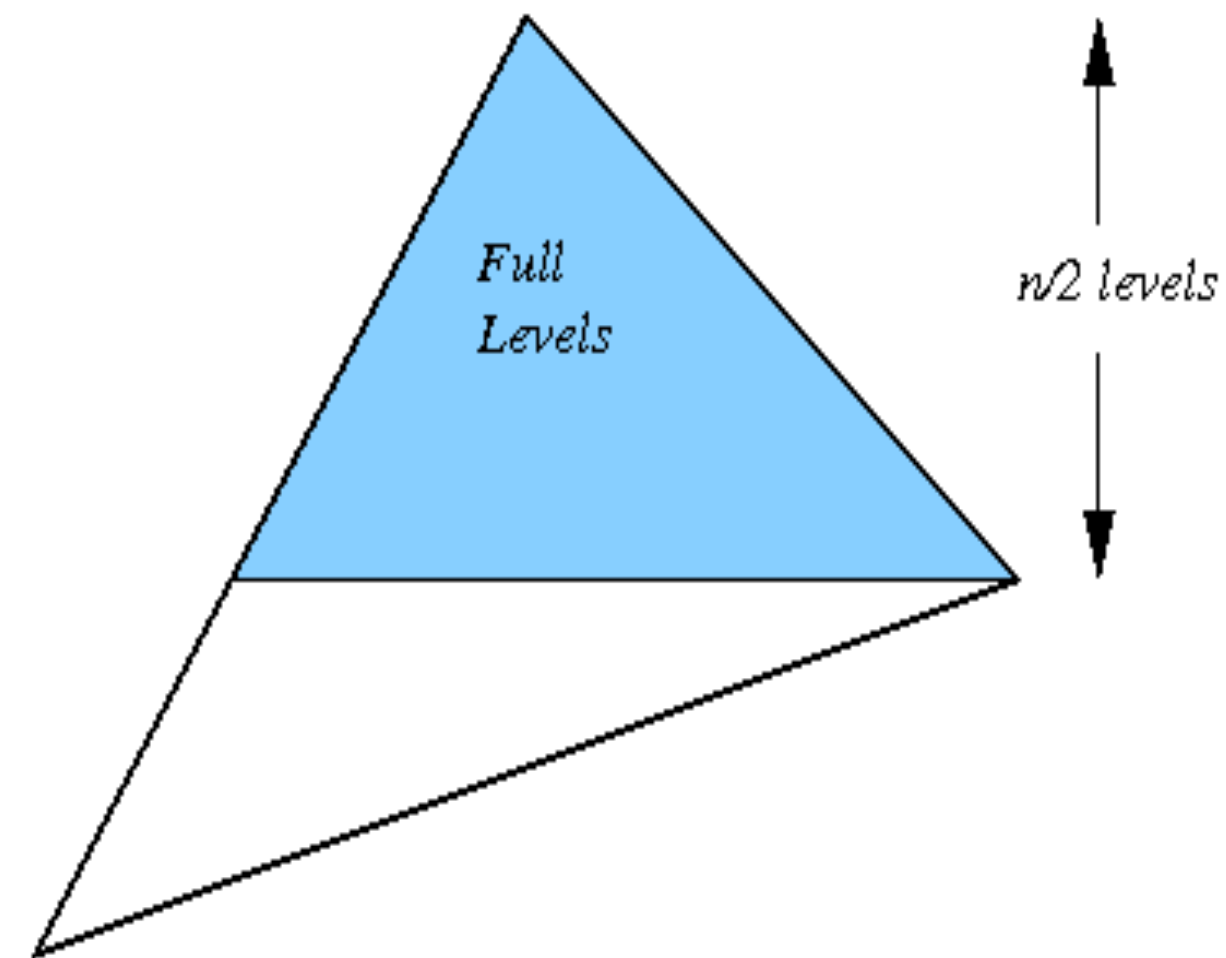
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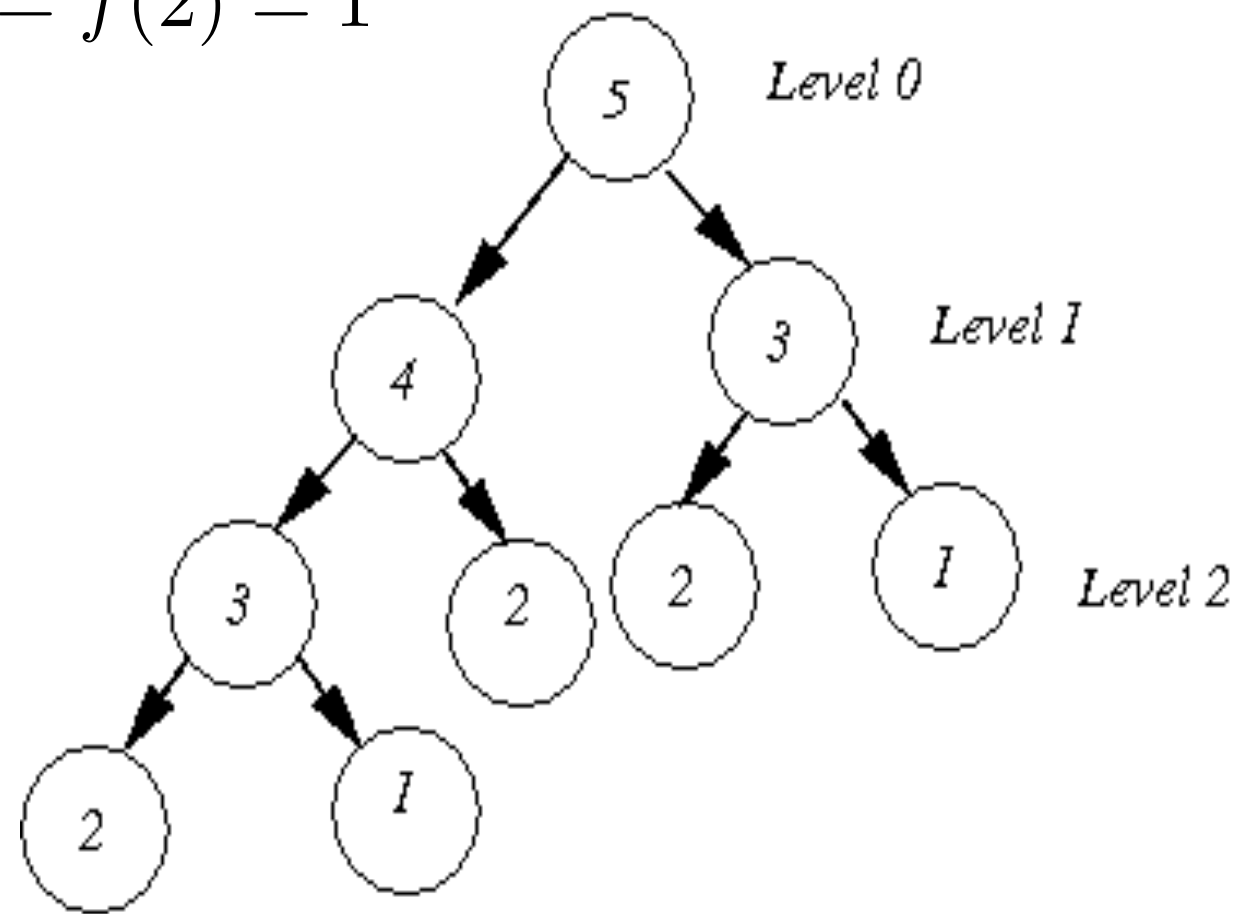


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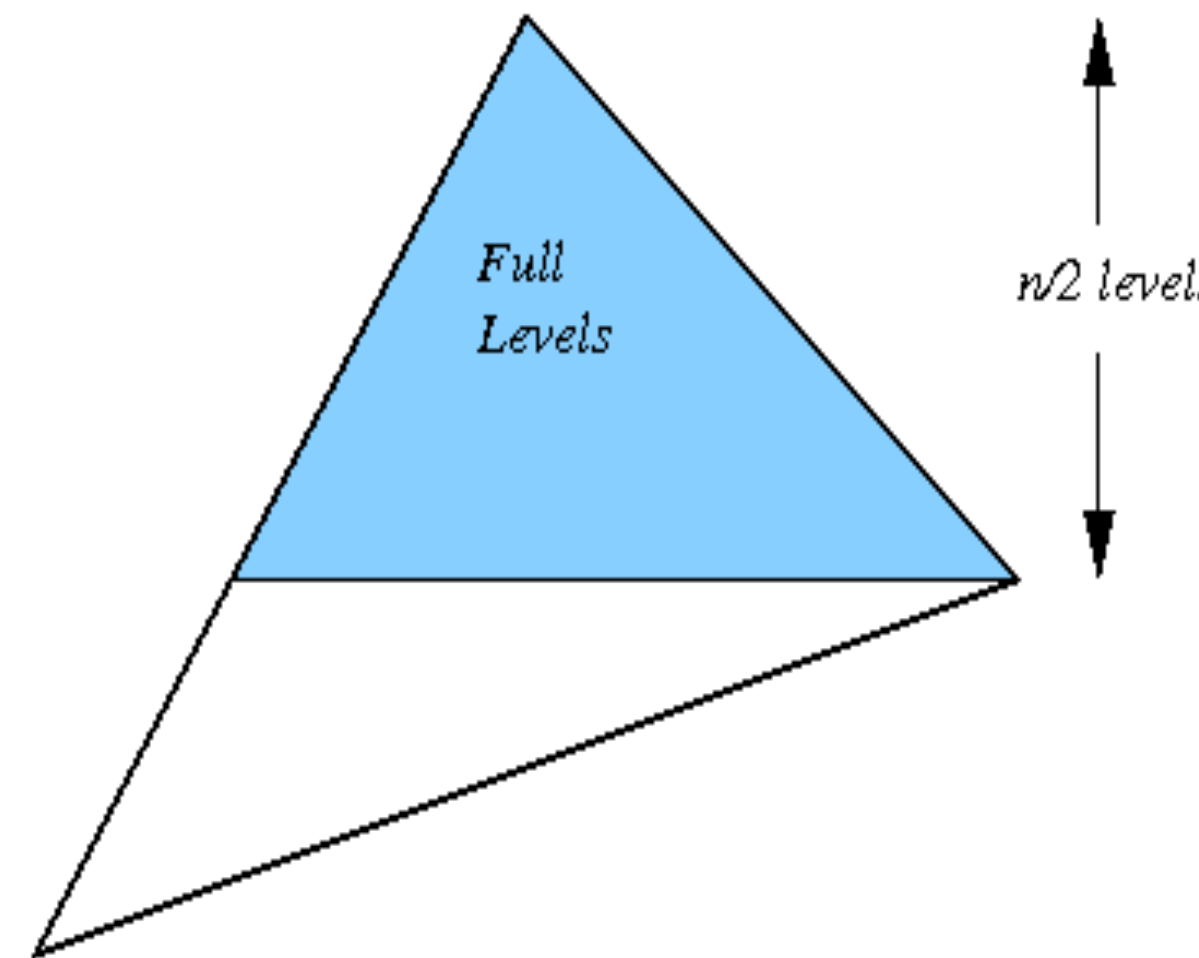
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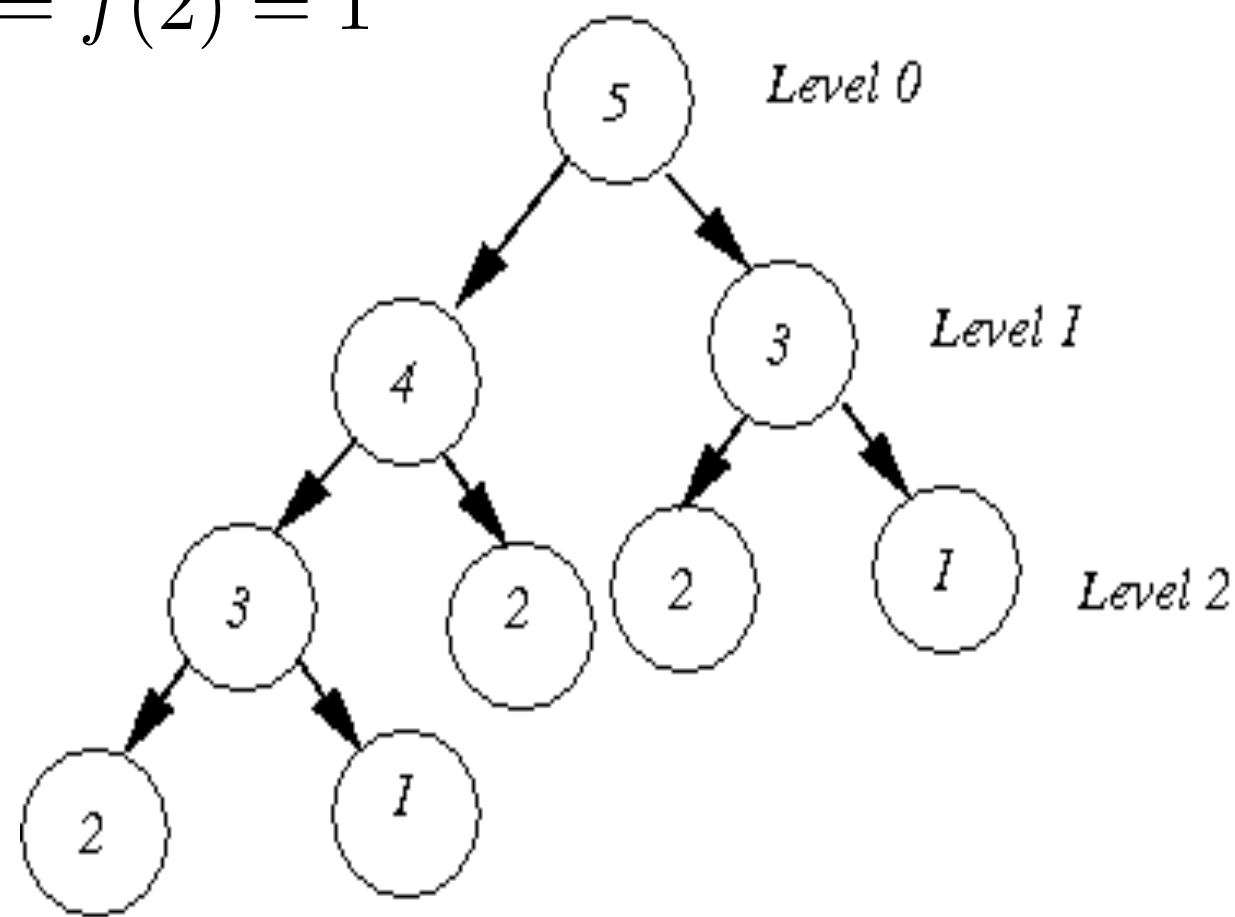
naive recursion  
without  
memoization:  
 $O(1.618...^n)$

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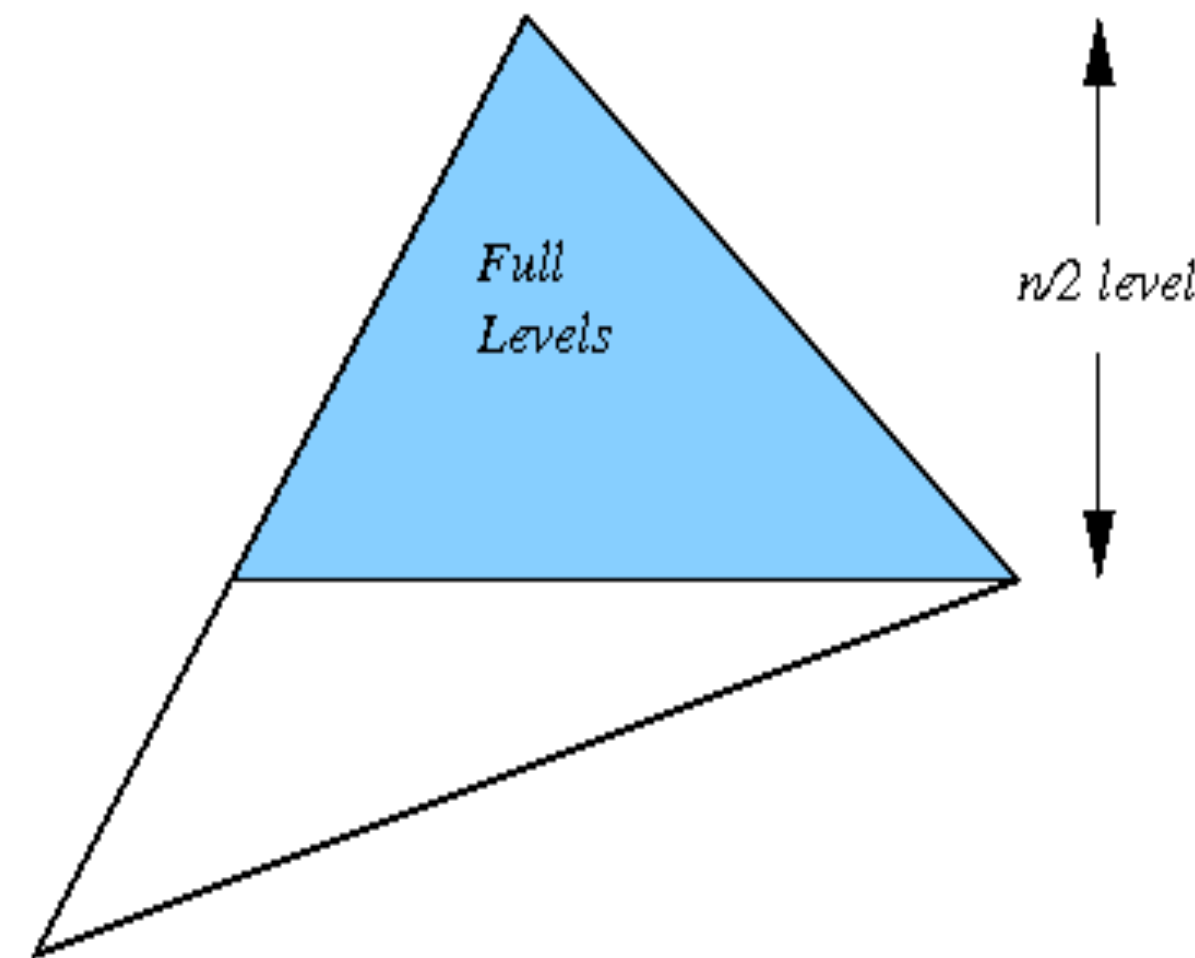
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DPI: top-down with memoization:  $O(n)$

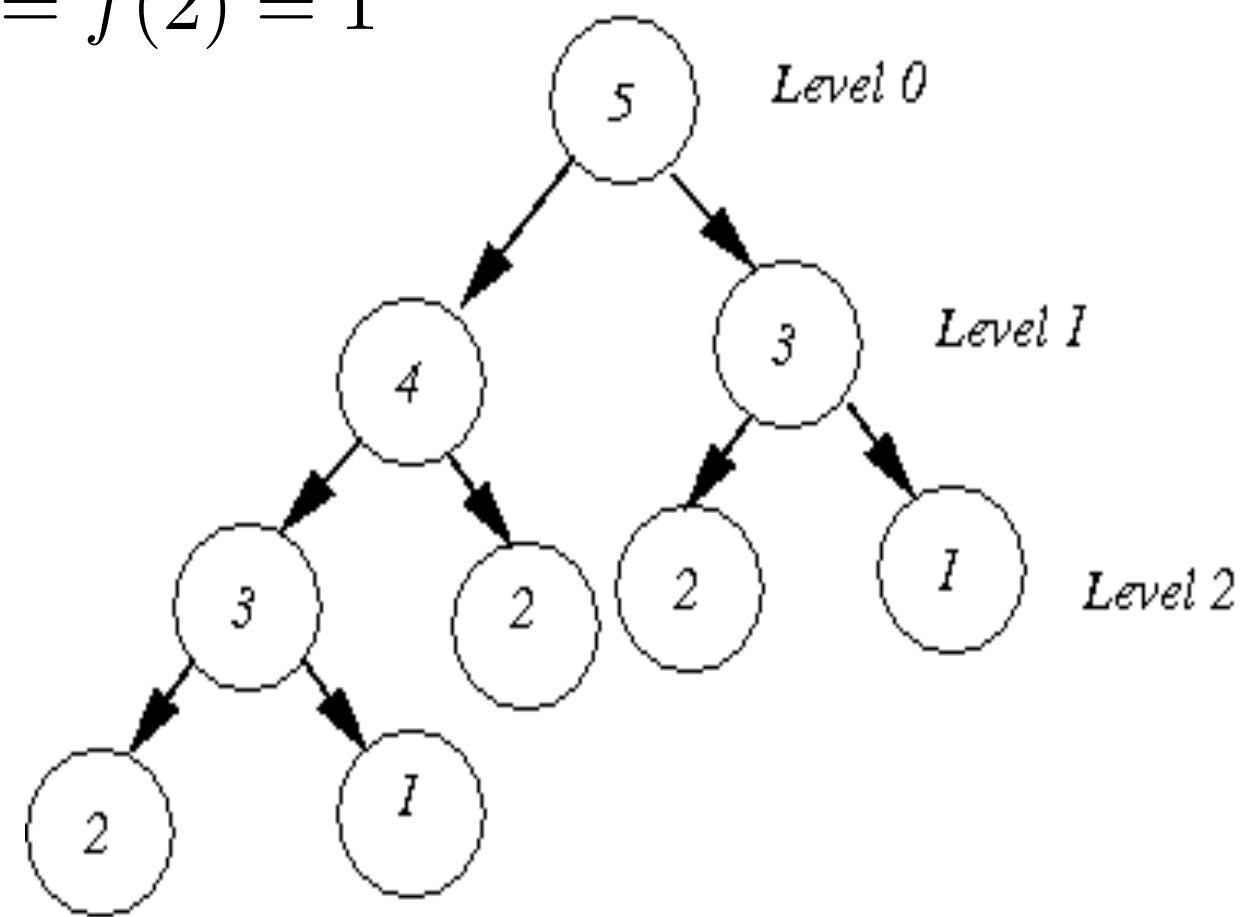
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fibs={1:1, 2:1} # hash table (dict)  
def fib1(n):  
    if n not in fibs:  
        fibs[n] = fib1(n-1) + fib1(n-2)  
    return fibs[n]
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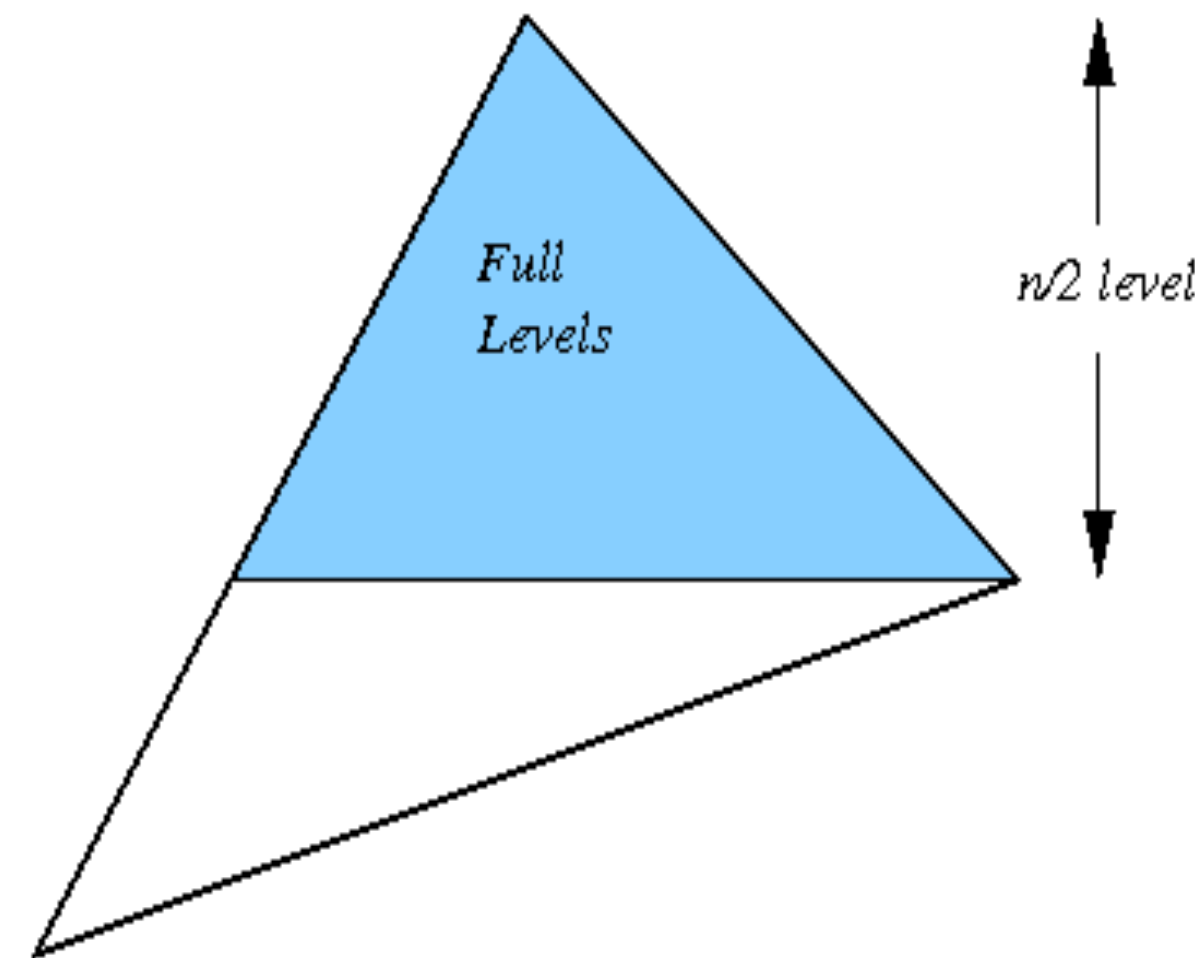


DP2: bottom-up:  $O(n)$

```
def fib0(n):
    a, b = 1, 1
    for i in range(3, n+1):
        a, b = a+b, a
    return a
```

```
def fib0(n):
    f = [1, 1]
    for i in range(3, n+1):
        f.append(f[-1]+f[-2])
    return f[-1]
```

```
def fib(n):
    if n <= 2:
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naive recursion  
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DP1: top-down with memoization:  $O(n)$

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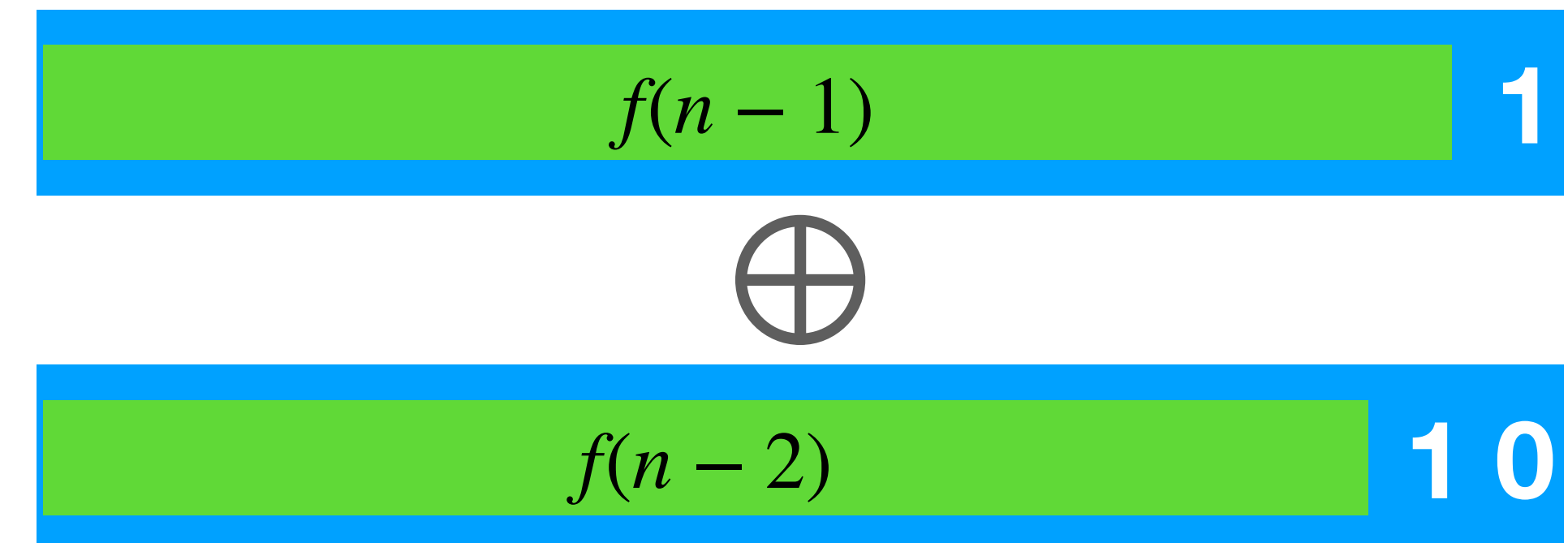
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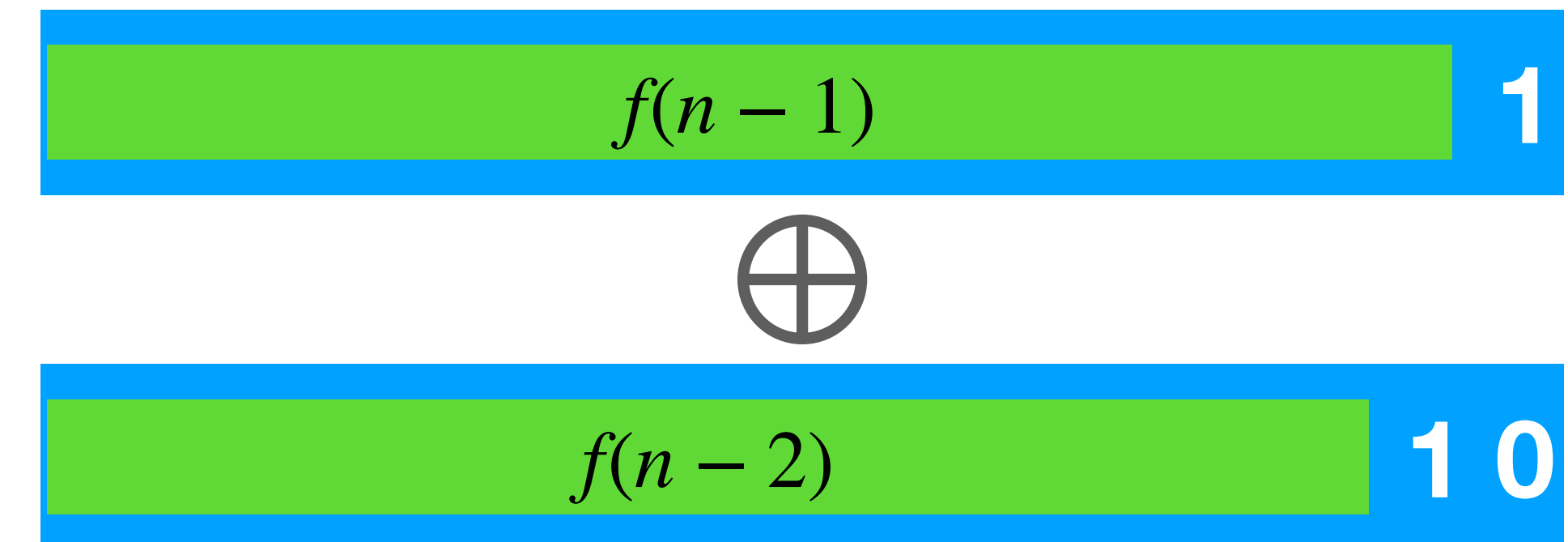
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$$f(n) = f(n-1) + f(n-2)$$

$$f(1) = 2, \quad f(0) = 1$$



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- max weighted independent set on a linear-chain graph
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$$f(0) = 0; f(1) = a[1]?$$

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$i$	-1	0	1	2	3	4	5	6
$a[i]$			9	10	8	5	2	4
$f(i)$								

*best value*  
*backpointer*

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$f(i)$	0	0	9					

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*best value*  
*backpointer*  
*start here* ←

recursively backtrack  
the optimal solution

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$b(i)$			T	T	T	F	T	T

best value  
backpointer  
start here

recursively backtrack  
the optimal solution

# Max Independent Set (MIS)

- max weighted independent set on a linear-chain graph

- e.g. **9** — 10 — **8** — 5 — 2 — **4** ; best MIS: [9, 8, 4] = 21 (vs. greedy: [10, 5, 4] = 19)

- subproblem:  $f(i)$  -- max independent set for  $a[1]..a[i]$  (1-based index)

$$f(i) = \max\{f(i-1), f(i-2) + a[i]\}$$

$$f(0) = 0; f(1) = a[1]?$$

$b(i) = [f(i) \neq f(i-1)]$  : take  $a[i]$  for  $f(i)$ ?

No!  $f(1) = \max\{a[1], 0\}$

or even better:  $f(0) = 0; f(-1) = 0$

$i$	-1	0	1	2	3	4	5	6
$a[i]$			9	10	8	5	2	4
$f(i)$	0	0	9	10	17	17	19	21
$b(i)$			T	T	T	F	T	T
back track	*		* take		* take	* not		* take

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recursively backtrack  
the optimal solution

MIS

$$f(n) = \max \left\{ \begin{array}{l} f(n-1) + 0 \\ f(n-2) + a[n] \end{array} \right.$$

bitstrings

$$f(n) = \left\{ \begin{array}{l} f(n-1) \times 1 \\ f(n-2) \times 1 \end{array} \right.$$

summary operator  $\oplus$  (across divides)

combination operator  $\otimes$  (within a divide)

# Graph Interpretation of DP

- MIS: longest path between source and target (see lecture video)
  - each node  $i$  has two incoming edges:  $(i - 2) \xrightarrow{a[i]} i$  (take) and  $(i - 1) \xrightarrow{0} i$  (not take)
  - $f(i)$ : longest path between source and node  $i$
- fibonacci & bitstrings: number of paths between source and target

# Summary

- Divide-and-Conquer = divide + conquer + combine
- Dynamic Programming = **multiple** divides + **memoized** conquer + **summarized** combine
- two implementation styles
  - 1. recursive top-down + memoization
  - 2. bottom-up
- backtracking to recover best solution for optimization problems
  - 1. backpointers (recommended); 2. store subsolutions (not recommended — often slows down); 3. recompute on-the-fly
- two operators:  $\oplus$  for summary (across multiple divides) and  $\otimes$  for combine (within a divide)
- counting problems vs. optimization problems (“cost-reward model”)
- three steps in solving a DP problem
  - define the subproblem
  - recursive formula
  - base cases

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$$f(n) = \underset{\substack{\text{summary} \\ \text{operator } \oplus \\ \text{(across divides)}}}{\max} \left\{ \begin{array}{l} \overset{\text{cost}}{f(n-1)} \overset{\text{reward}}{+ 0} \\ \overset{\text{cost}}{f(n-2)} \overset{\text{reward}}{+ a[n]} \end{array} \right.$$

combination operator  $\otimes$  (within a divide)

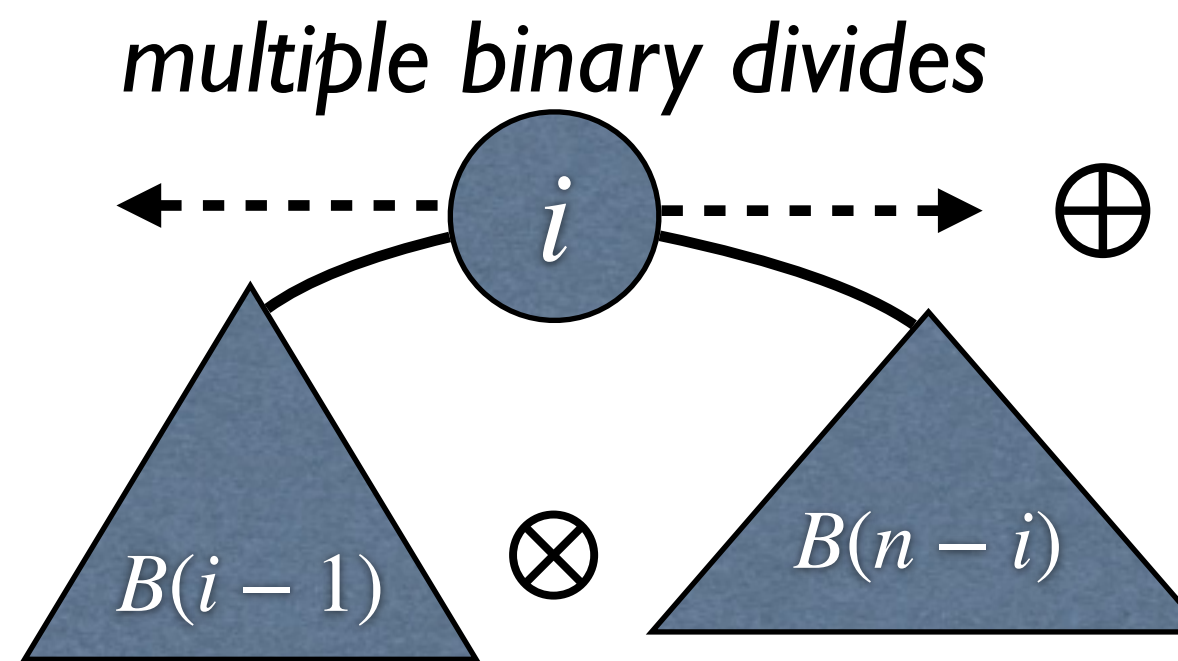


# Deeper Understanding of DP

- divide-n-conquer
  - single divide, independent conquer, combine
- DP = **divide-n-conquer with multiple divides**

- for each possible divide

- divide
- conquer with memoization



- combine subsolutions using the combination operator  $\otimes$

- summarize over all possible divides using the summary operator  $\oplus$

- multiple divides  $\Rightarrow$  overlapping subproblems

$$B(n) = \oplus_{i=1}^n (B(i-1) \otimes B(n-i))$$

- each single divide  $\Rightarrow$  independent subproblems!

$$B(0) = 1$$

	$\oplus$	$\otimes$
Fib	+	x
MIS	max	+
# BSTs	+	x
knapsack	max	+
shortest path	min	+

# Unary vs. Binary Divides

$$(a) : T(n) = 2T(n/2) + \dots$$

$$(b) : T(n) = T(n-1) + \dots$$

$$(c) : T(n) = T(n/2) + \dots$$

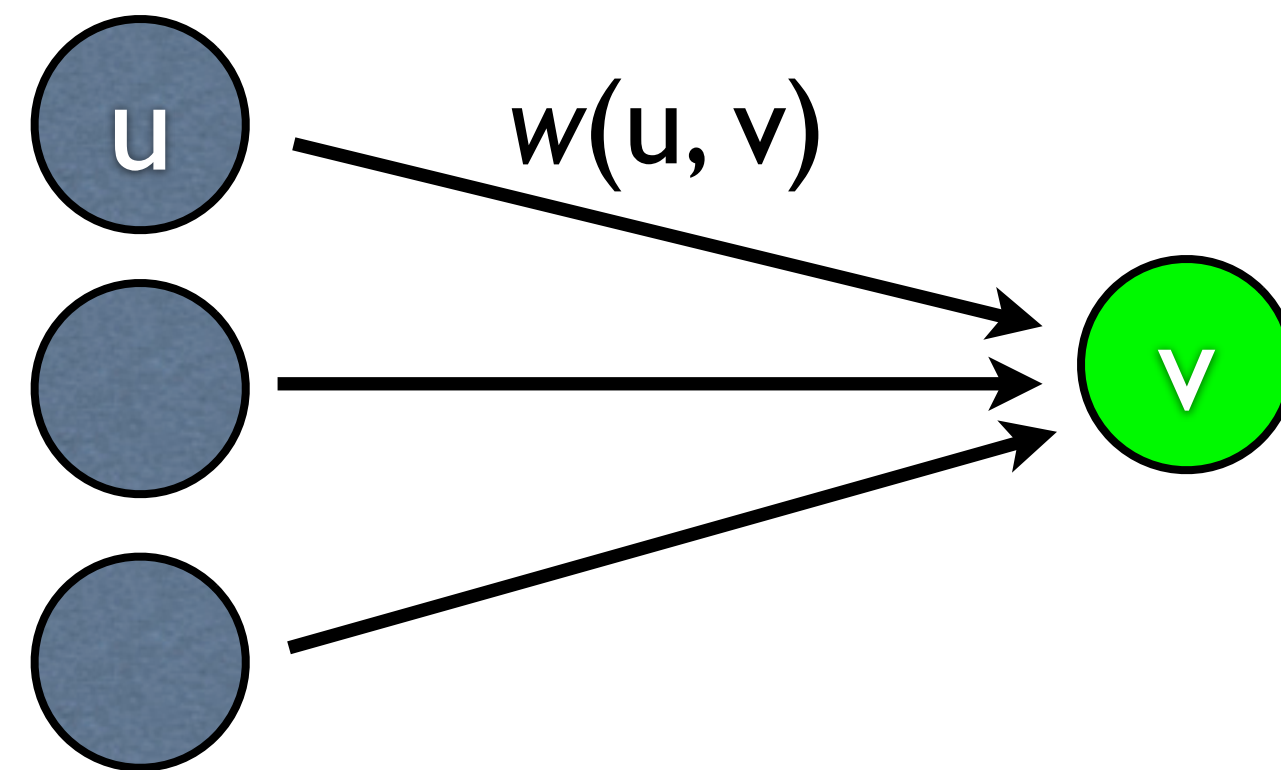
	branching (binary divide)	one-sided (unary divide)
divide-n-conquer	quicksort, best-case	quicksort, worst-case (b)
	mergesort	quickselect: worst (b), best (c)
	(balanced) tree traversal (DFS)	binary search: (c)
	heapify (top-down)	search in BST: worst (b), best (c)
DP	# of BSTs (hw5), <i>midterm</i>	Fib, # of bitstrings (hw5)...
	optimal BST, <i>final</i>	max indep. set (hw5)
	RNA folding (hw10)	knapsack (hw6), <i>midterm</i>
	context-free parsing	Viterbi (hw8), <i>final</i>
	matrix-chain multiplication, ...	LCS, LIS, edit-distance,...

# Two Divides vs. Multiple Divides (# of Choices)

	two divides	multiple divides
DP	Fib, # of bitstrings (hw5)...	# of BSTs (hw5)
	max indep. set (hw5)	unbounded knapsack (hw6)
	0-1 knapsack (hw6)	bounded knapsack (hw6)
		Viterbi (hw8)
		RNA folding (hw10)

# Viterbi Algorithm for DAGs

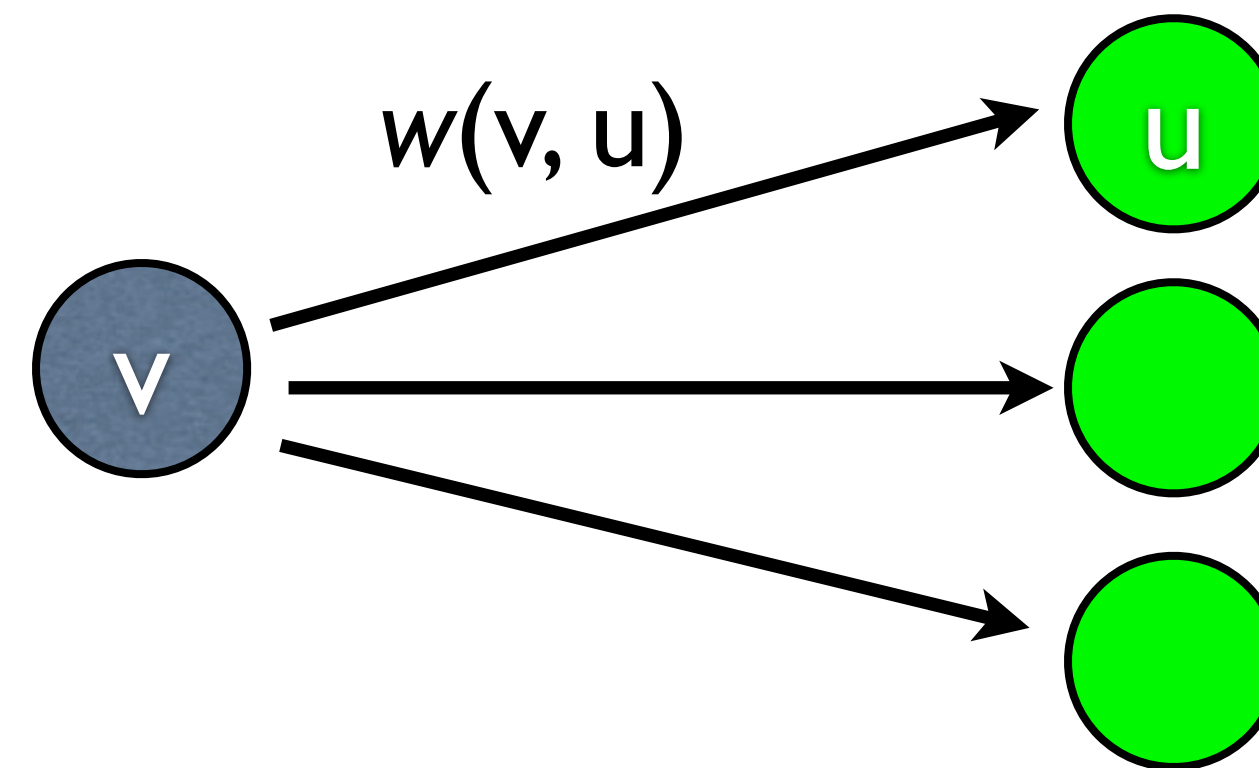
1. topological sort
2. visit each vertex  $v$  in sorted order and do updates
  - for each **incoming** edge  $(u, v)$  in  $E$
  - use  $d(u)$  to update  $d(v)$ :  $d(v) \oplus = d(u) \otimes w(u, v)$
  - key observation:  $d(u)$  is fixed to optimal at this time



- time complexity:  $O(V + E)$

# Variant 1: forward-update

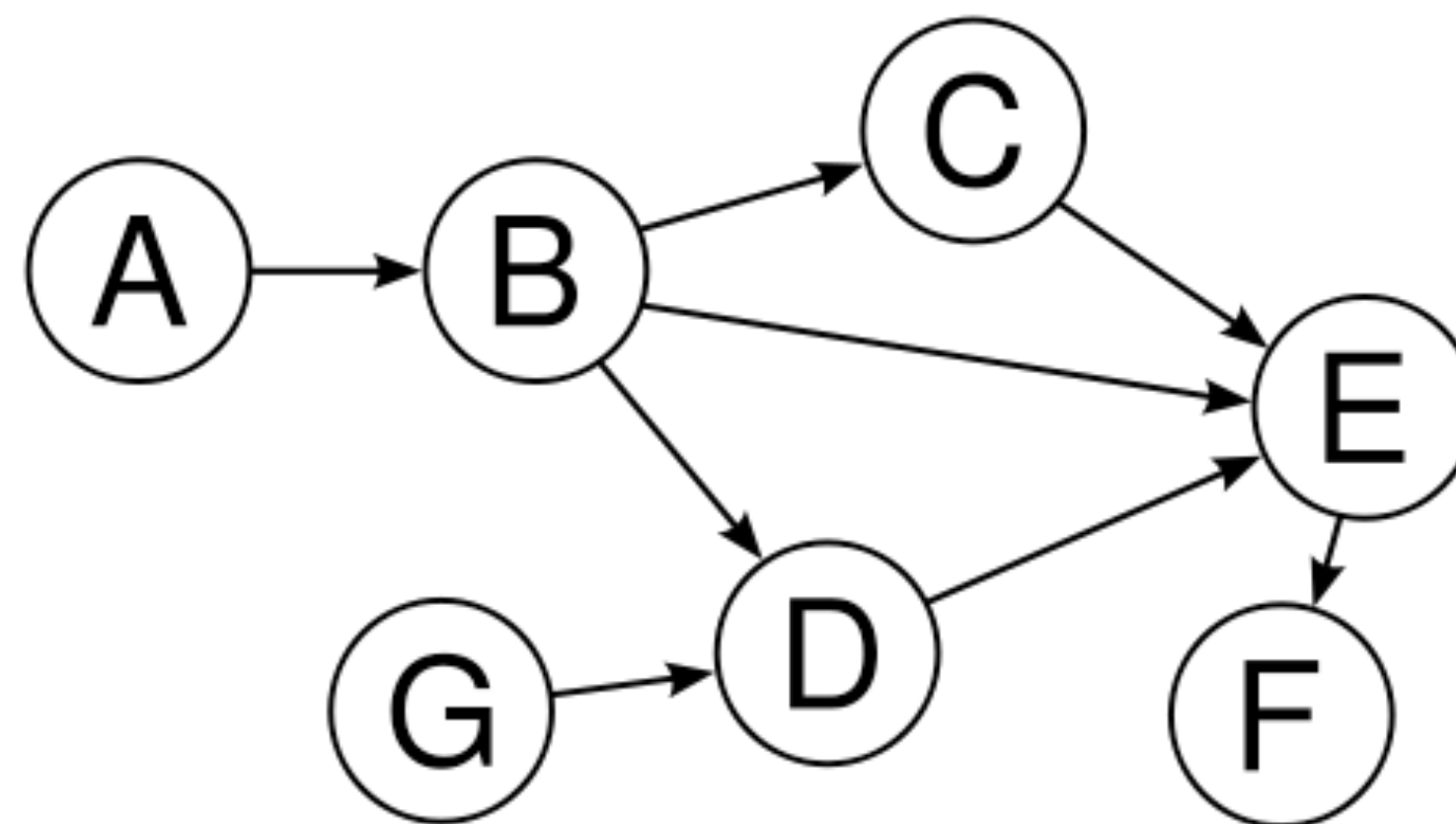
1. topological sort
2. visit each vertex  $v$  in sorted order and do updates
  - for each **outgoing** edge  $(v, u)$  in  $E$
  - use  $d(v)$  to update  $d(u)$ :  $d(u) \oplus = d(v) \otimes w(v, u)$
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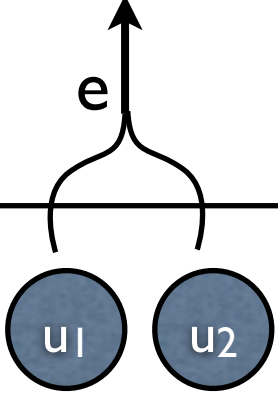
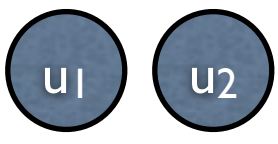
- time complexity:  $O(V + E)$

# Variant 2: Recursive Descent

- Top-down Recursion + Memoization = Bottom-up
- Start from the target vertex, going backwards
  - remember each visited vertex
- Sometimes easier to implement
- There is a tradeoff b/w top-down and bottom-up

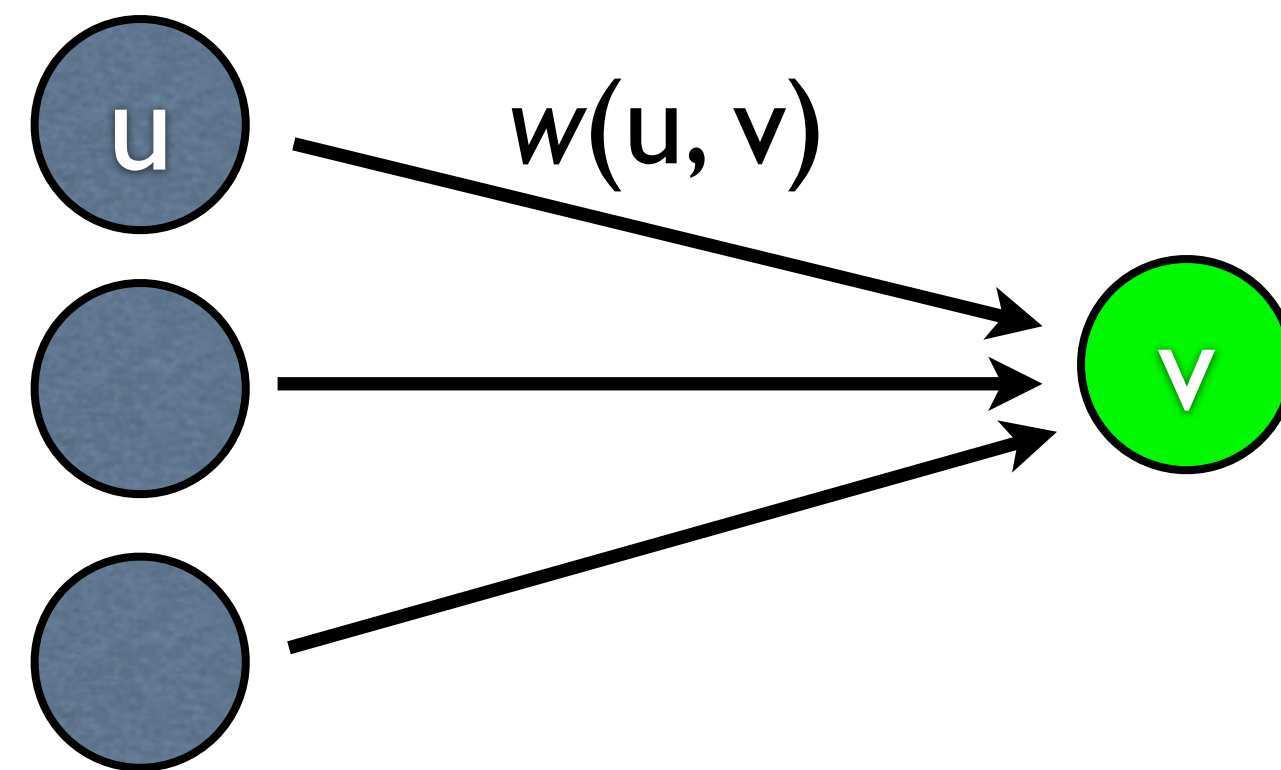


# One-way vs. Two-way Divides (Graph vs. Hypergraph)

	two-way (binary divide)	one-way (unary divide)
divide-n-conquer	quicksort, best-case	quicksort, worst-case
	mergesort	quickselect
	tree traversal (DFS)	binary search
	heapify (top-down)	search in BST
DP	 # of BSTs (hw5)	Fib, # of bitstrings (hw5)...
	 optimal BST	max indep. set (hw5)
	 RNA folding (hw10)	knapsack (all kinds, hw6)
	context-free parsing	Viterbi (hw8)
	matrix-chain multiplication, ...	LCS, LIS, edit-distance, ...

# Viterbi Algorithm for DAGs

1. topological sort
2. visit each vertex  $v$  in sorted order and do updates
  - for each **incoming** edge  $(u, v)$  in  $E$
  - use  $d(u)$  to update  $d(v)$ :  $d(v) \oplus = d(u) \otimes w(u, v)$
  - key observation:  $d(u)$  is fixed to optimal at this time

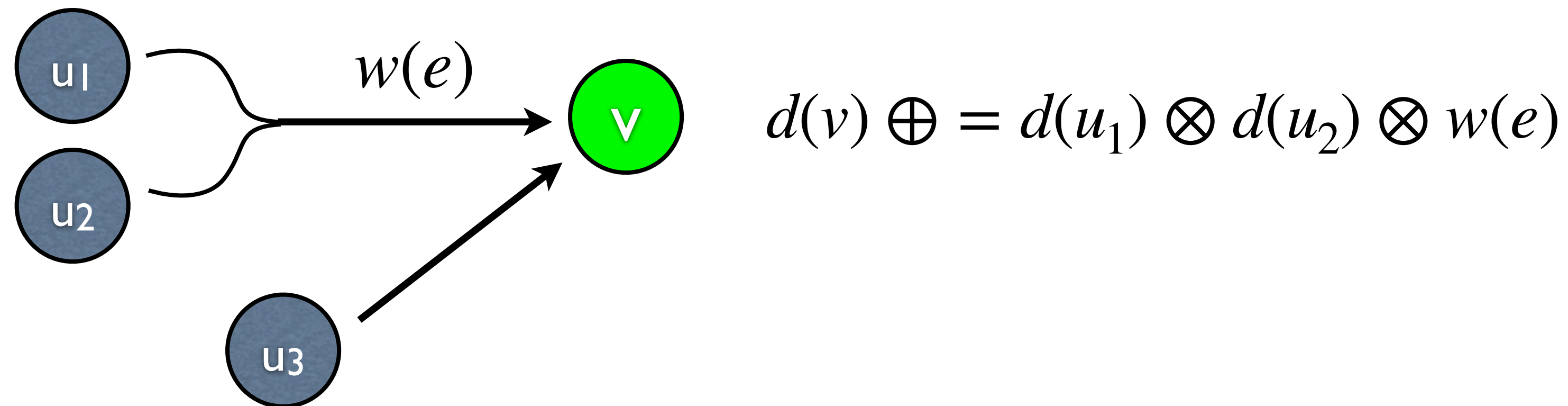


- time complexity:  $O(V + E)$



# Viterbi Algorithm for DAHs

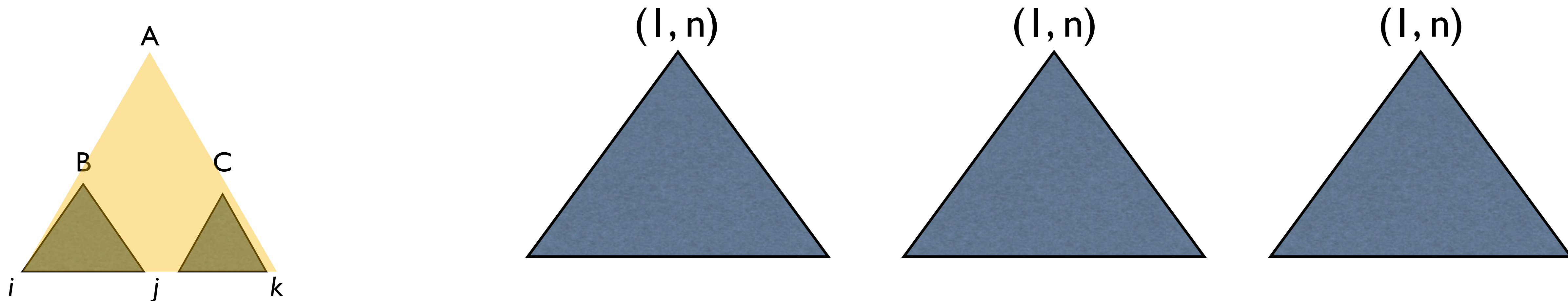
1. topological sort
2. visit each vertex  $v$  in sorted order and do updates
  - for each incoming **hyperedge**  $e = ((u_1, \dots, u_{|e|}), v, w(e))$
  - use  $d(u_i)$ 's to update  $d(v)$
  - key observation:  $d(u_i)$ 's are fixed to optimal at this time



- time complexity:  $O(V + E)$  (assuming constant arity)

# Example: RNA Folding and CKY Parsing

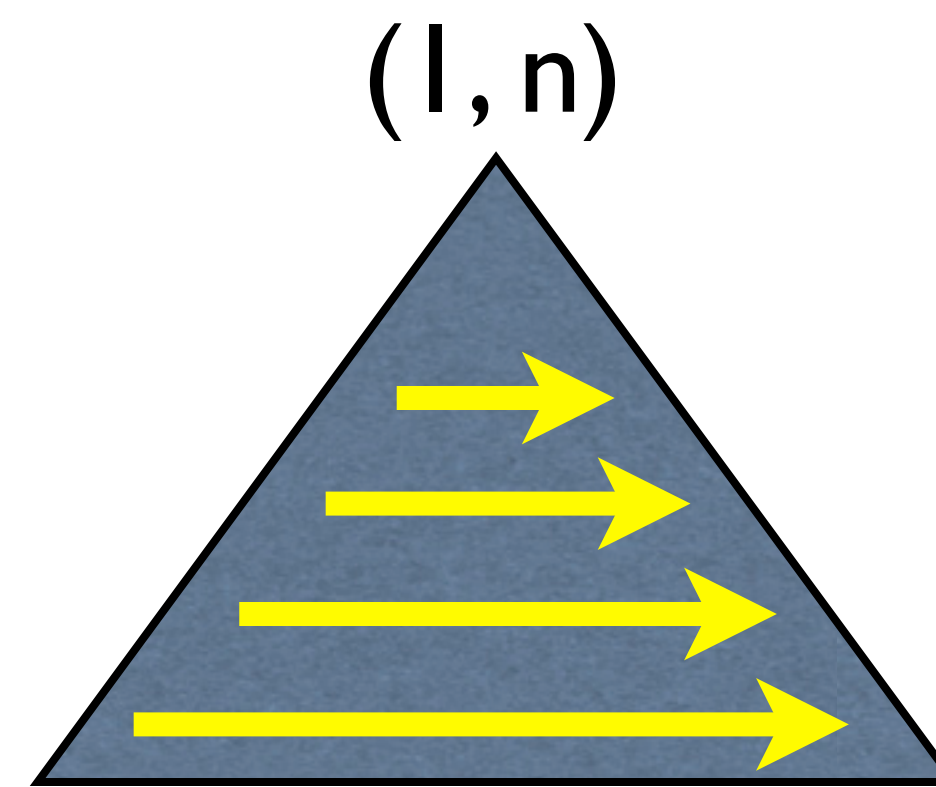
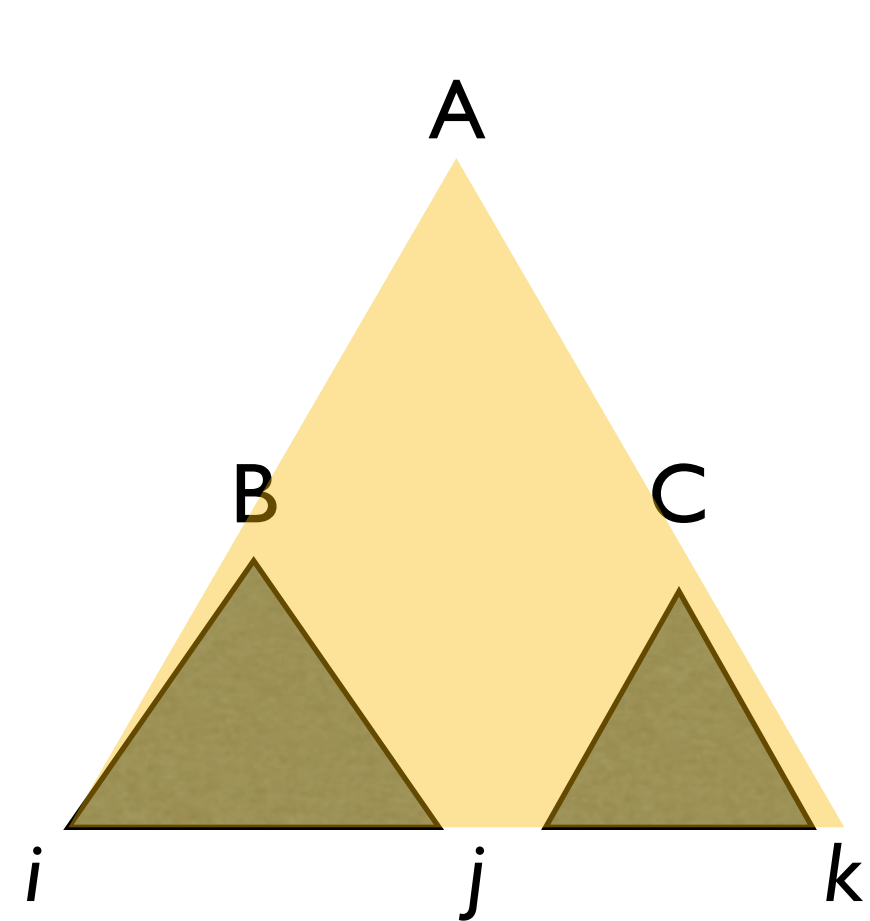
- typical instance of the generalized Viterbi for DAHs
- many variants of CKY ~ various topological ordering
- Nussinov algorithm in RNA is almost identical to CKY but w/o overcounting



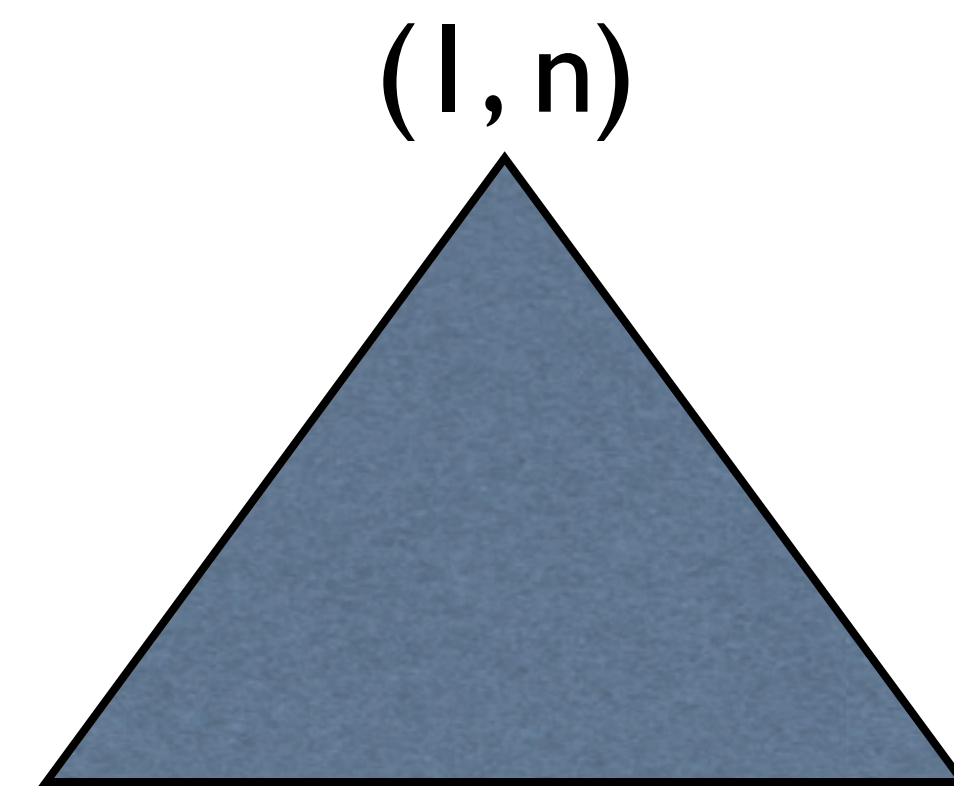
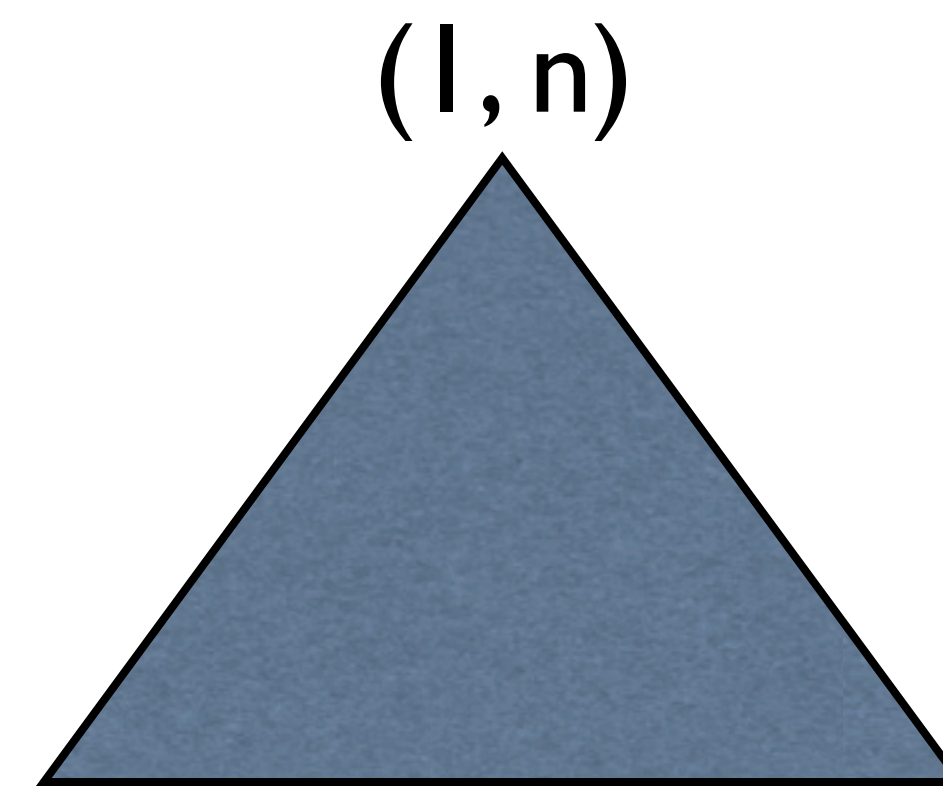
all  $O(n^3)$

# Example: RNA Folding and CKY Parsing

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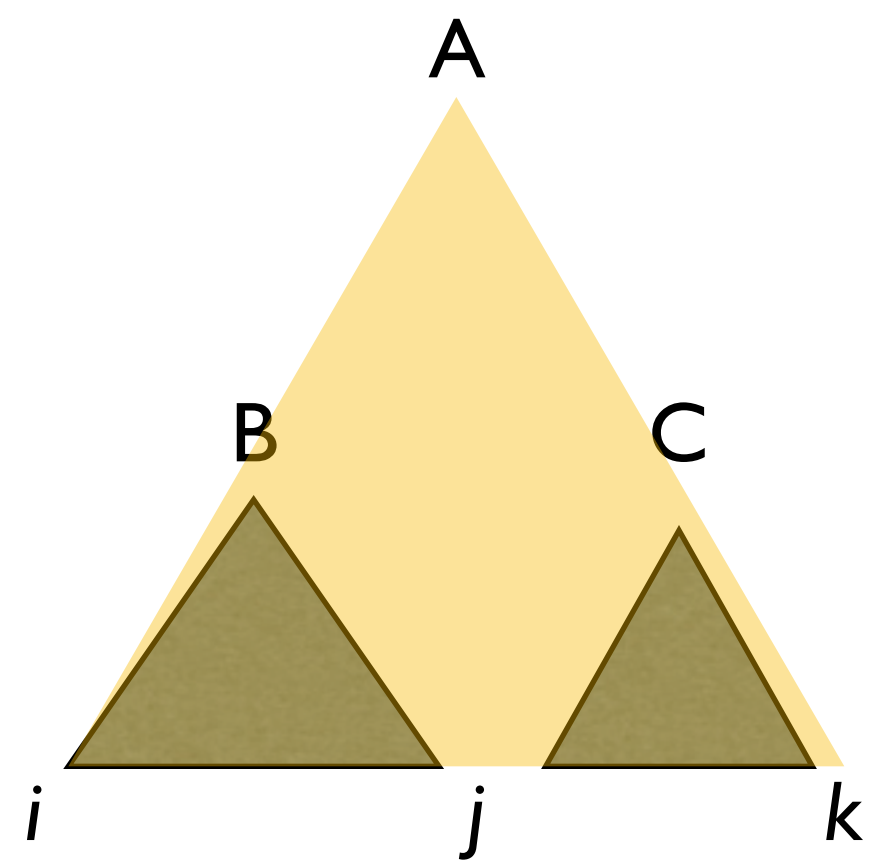
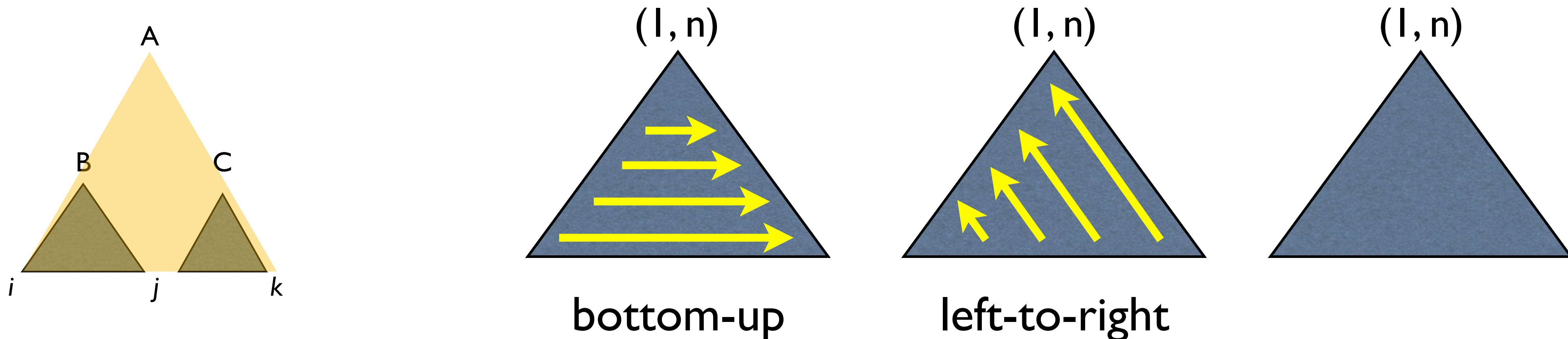
bottom-up



all  $O(n^3)$

# Example: RNA Folding and CKY Parsing

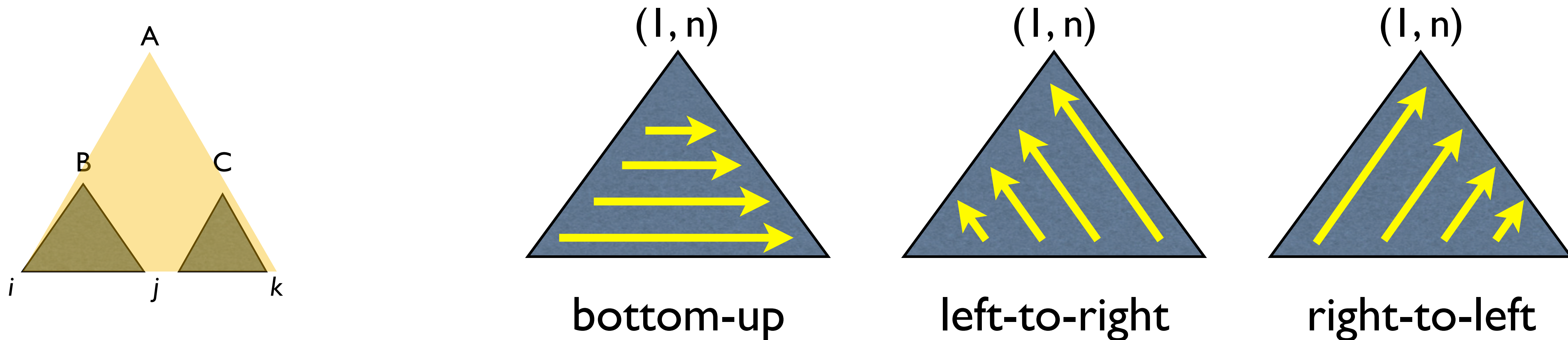
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all  $O(n^3)$

# Example: RNA Folding and CKY Parsing

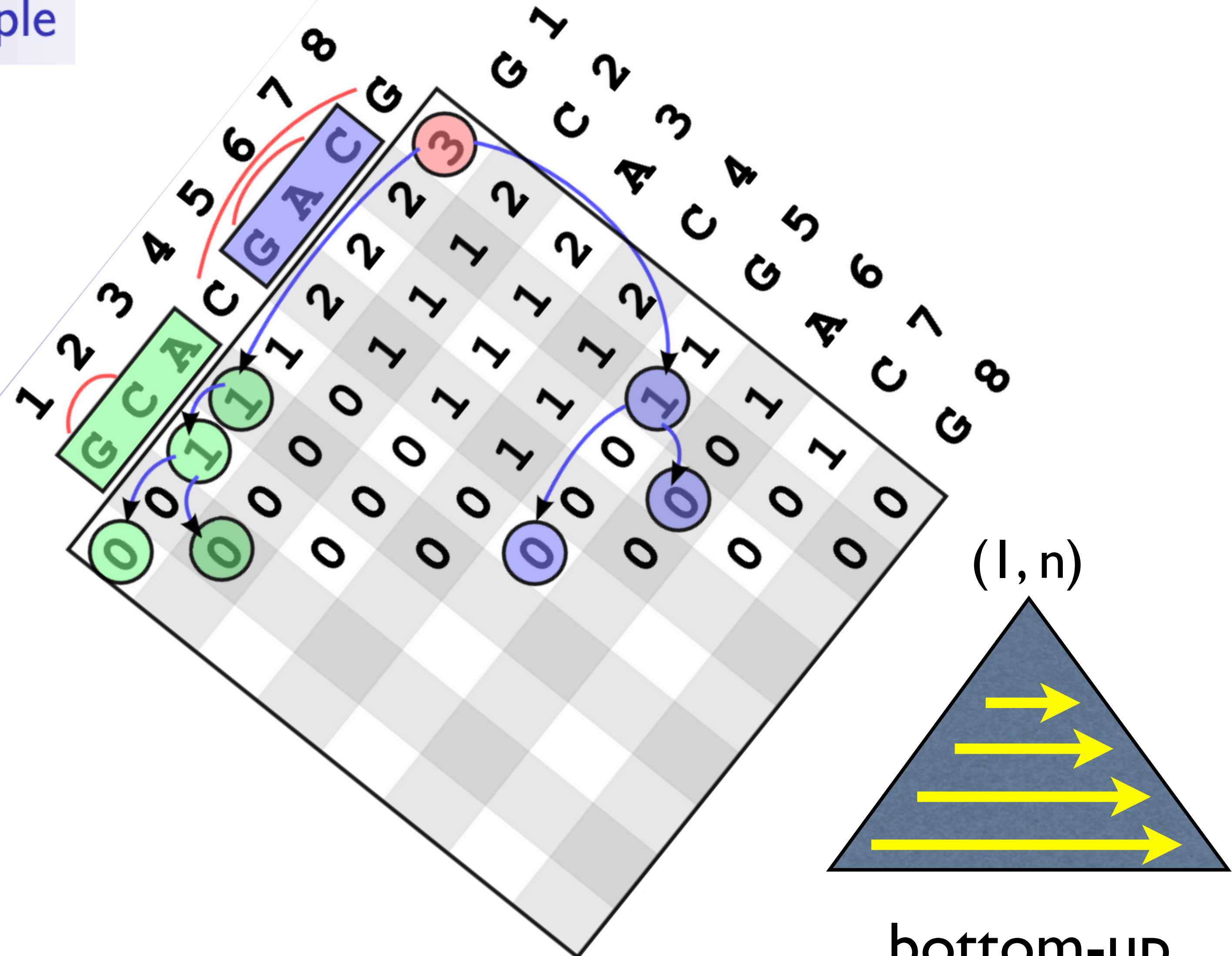
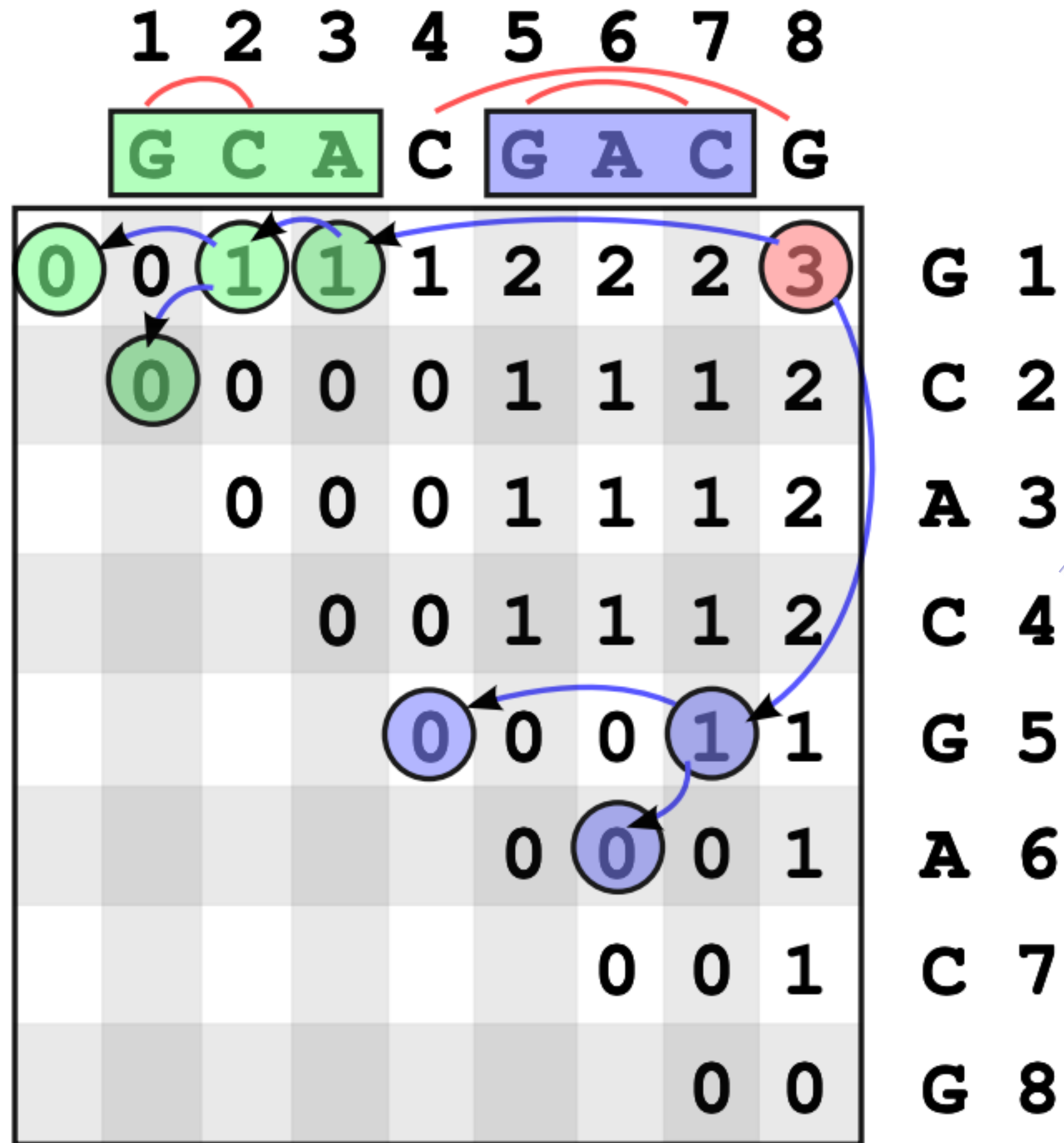
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all  $O(n^3)$

# RNA Folding Example

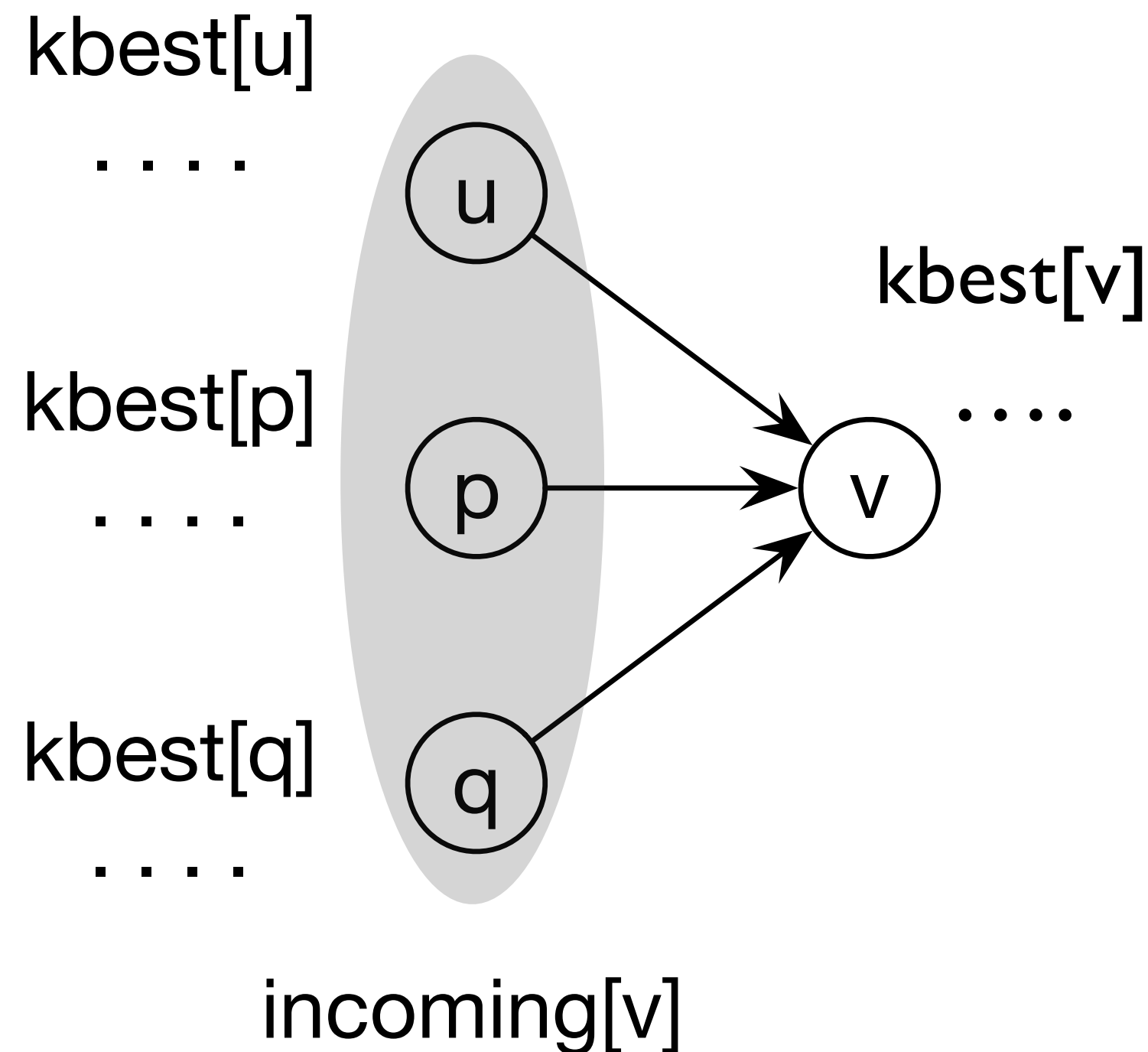
## Nussinov Algorithm — Traceback Example



# k-best Viterbi on Graph

- simple extension of Viterbi to solve k-best on graphs and hyper graphs

cf. teams problem in HW4



for each node  $v$ ,

compute its kbest distances

from the kbest of each incoming node  $u$

1-best:  $O(E + V)$

k-best:  $O(E + Vk \log d_{\max})$  where  $d_{\max}$  is the max in-degree

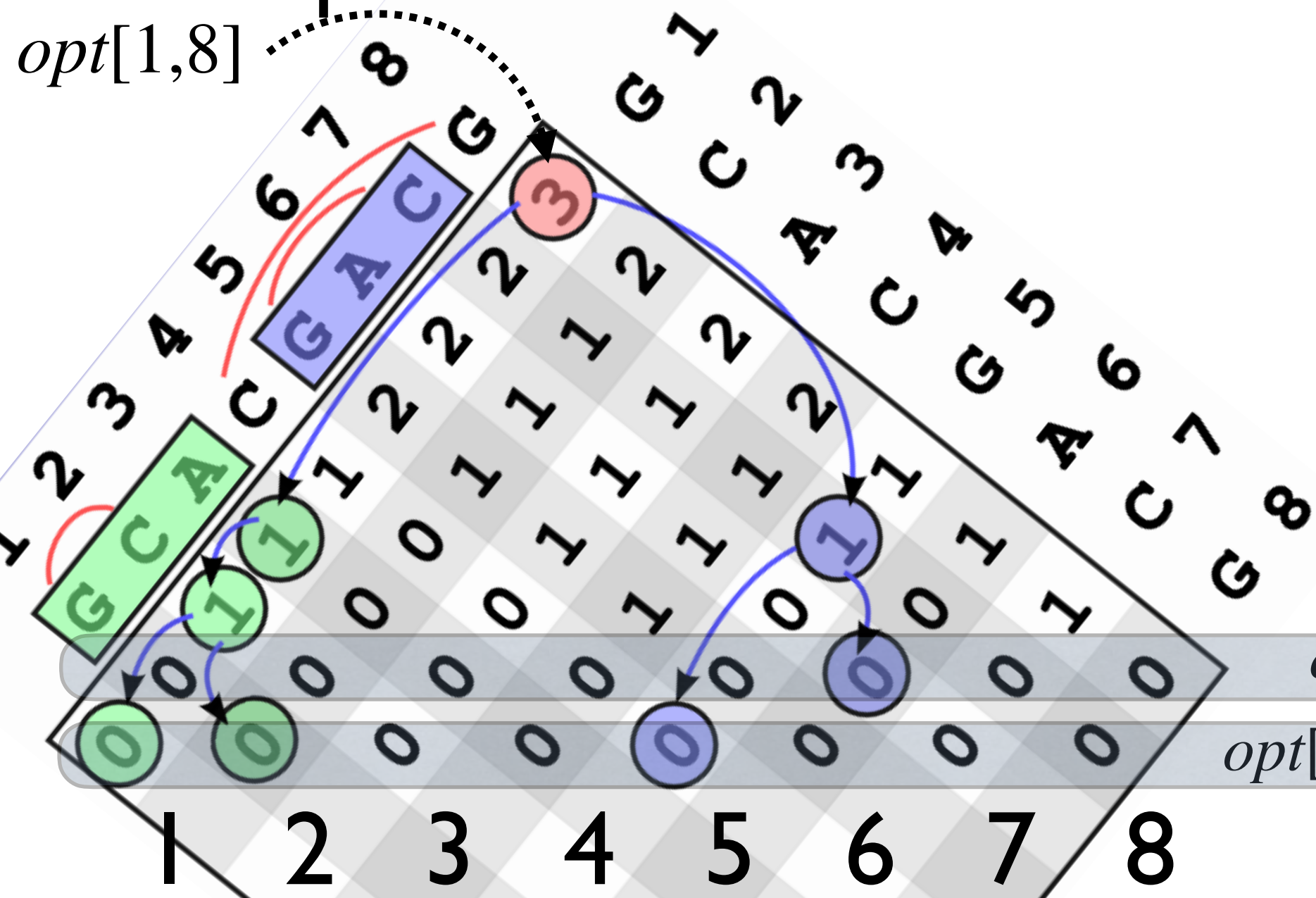
can improve it to: (cf. midterm & teams, w/ quickselect)

k-best:  $O(E + Vk \log k)$  (assume  $k \ll d_{\max}$ )

(“most states do not have anybody on team USA”)

# k-best Viterbi on Hypergraph

- simple extension of Viterbi to solve k-best on graphs and hyper graphs cf. midterm



12345678  
GCACGACG  
(k = 3)

12345678  
GCACGACG

+0 (unary)

12345678  
GCACGACG  
( )

12345678  
GCACGACG  
( )

+|

+|

+|

1234567  
GCACGAC

34567  
ACGAC

567  
GAC

""

$$opt[i, j] = \oplus \begin{cases} opt[i, j-1], \\ \oplus_{i \leq p < j} (opt[i, p-1] \otimes opt[p+1, j-1] \otimes 1) \end{cases}$$

$$opt[i, i] = opt[i, i-1] = 1_{\otimes}$$

<b>opt</b>	$\oplus$	$\otimes$	$1_{\otimes}$
<b>best</b>	max	+	0
<b>total</b>	+	x	1

2
2
2

	1	1	0
1	0	2	2
G	2	2	1

	1	0
1	3	2
0	2	1

	0
2	3
1	2
1	2

kbest ("GCACGACG", 3) = [(3, '().((.)')), (3, '().().().'), (2, '().().().')]