## CS 261-020 Data Structures

Lecture 4 Dynamic Array vs. Linked List Begin Complexity Analysis 1/25/24, Thursday



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## Odds and Ends

- Assignment 1 Due Sunday midnight on TEACH
  - No function headers needed if they are already provided
  - Require in-line comments & program header

#### Recap: C Basics – Function pointers

- When implementing sort() function:
  - This function needs to be able to sort an array of any data type
    - Thus, each element is void\*, and we need to use void\*\* to control an array of void\*
  - The function needs the size of the array, since it is dynamic
  - The function needs a comparison method to determine which element comes first
    - The method will be provided by the calling function, thus we need to use a function pointer to store the address of that method/function

void sort(void\*\* arr, int n, int (\*cmp)(void\* a, void\* b));

- Within sort():
  - Whenever we need to compare two values from the array being sorted, we can just call cmp()

#### Recap: C Basics – Function pointers

- For the calling function (when use sort()):
  - Knows the data type of each element of the array to be sorted
  - Knows the size of the array
  - Knows how to compare the two elements in the array

```
int compare_ints(void* a, void* b) {
    int* ai = a, *bi = b; /* Cast void* back to int*. */
    if (*ai < *bi)
        return 0;
    else
        return 1;
}</pre>
```

• Function call will be:

sort((void\*\*)array\_of\_ints, number\_of\_ints, compare\_ints);

## FYI: Using GDB

• Compile with debugging symbols (-g flag), e.g.:

gcc -std=c99 filename.c -g -o exe\_name

• Run it with GDB:

gdb ./exe\_name

#### FYI: Common GDB Commands

- 1. break set up break points, e.g.: b \*main break 10
- 2. run begin execution (until a break point)
- 3. print see the values of data, e.g. print i print &ptr print &main
- ✓ 4. next and step step line by line through the program
  - 5. continue continue until a break point OR the end of the program
  - 6. backtrace prints a backtrace of all stack frame (locate seg fault !!!)
- 7. x/100wx [address or register] read memory
  - Examine
  - **100** values
  - sized as word (w, 4 bytes)
    - b byte
    - g 8 bytes
  - In hexadecimal (x)
    - d decimal

## Lecture Topics:

- Dynamic Array (cont.)
- Linked List
- Begin Complexity Analysis

## Abstract Data Type (ADT)

- Abstract Data Type (ADT) a mathematical model for data types
- Specifies:
  - the type of data stored
  - the operations supported on them
  - the types of parameters of the operations.
- Why "abstract"?
  - an implementation-independent view of the data type

## **Dynamic Arrays**

- Elements in an array are stored in a contiguous block of memory
- Allow random access (direct access)
  - i.e., time to access the 1<sup>st</sup> element = time to access the last element
  - By using array subscript ([]):

```
int* array = malloc(1000 * sizeof(int));
array[0] = 0;
array[999] = 0;
```

## Dynamic Arrays (cont.)

- Basic operations:
  - get Gets the value of the element stored at a given index in the array
  - set Sets/updates the value of the element stored at a given index in the array
  - insert Inserts a new value into the array at a given index.
    - Sometimes, dynamic array implementations limit insertion to a specific location in the array, e.g. only at the end.

       2
       3
       4
       5
       1
       2
       4
       5
  - remove Removes an element at a given index from the array
    - Sometimes, dynamic array implementations avoid moving elements up a spot by only allowing the last element to be removed

## Dynamic Arrays (cont.)

- Drawbacks:
  - Fixed size, must be specified when the array is created
    - For static array:
    - int array[50];
    - For dynamic array:
    - int \*array = malloc (50 \* sizeof(int));
- $\rightarrow$ Need to allocate more memory if we need to store more data
  - How?
- Dynamic array DS doesn't have a fixed capacity
  - Has a variable size and can grow as needed



- size number of elements currently stored in the array
- capacity number of elements data has space for before it must be resized
- How it works?
  - An array of known capacity is maintained by the dynamic array DS.
  - As elements are inserted, they are simply stored in data
  - If an element is inserted into the dynamic array, and there isn't capacity for it in the underlying data storage array (data), the capacity of the underlying data storage array is doubled. Then the new element is inserted into this larger data storage array.





#### Inserting an element into dynarray

- Case 1: if size < capacity
  - At least one free spot in data
  - Insert the new element of index.



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- Case 2: if size == capacity
  - No free spot in data
  - Step 1: allocate a new array that has twice the capacity
  - Step 2: copy all elements from data to new array
  - Step 3: delete the old data array and update data
  - Step 4: Insert the new element





• Insert 16 to the following dynamic array:



• Step 1: allocate a new array that has twice the capacity

• Insert 16 to the following dynamic array:



• Step 2: copy all elements from data to new array

• Insert 16 to the following dynamic array:



• Step 3: delete the old data array and update data

• Insert 16 to the following dynamic array:



• Step 4: Insert the new element

#### **Common Mistakes**

- 1. dynarray\_create():
  - In order to manage a dynamic array, how many struct dynarray do you need?

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- 2. dynarray\_insert():
  - When size == capacity, do you need to free the entire struct dynarray, i.e., free(da), before resizing?

## Lecture Topics:

- Dynamic Array (cont.)
- Linked List
- Begin Complexity Analysis



- Elements in a linked list are stored in nodes and chained together
  - Not in contiguous memory
  - ★ Thus, no random access

Linear Data Structure

• A linked list in which each node points only to the next link in the list is known as a singly-linked list.



- Always contains as many nodes as it has stored values
  - Add an element  $\rightarrow$  allocate a node, add it to the list
  - Remove an element  $\rightarrow$  free the node from the list
- Many forms of linked list:
  - Keeps track only of the first element in the list, known as head



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- Many forms of linked list:
  - Keeps track only of the first element in the list, known as head
  - Keeps track of both the head of the list and the tail, or last element
  - Each node keeps track of both the *next* link and the *previous* link in the list, known as a doubly-linked list
  - Last node points to the first node, known as circular-linked list



- Many forms of linked list:
  - With sentinels, which are special nodes to designate the front/end of the list
    - E.g.: a doubly-linked list using both front and back sentinels



#### Inserting an element into linked list

- Where can we insert?
- ✓ Front/head
- ✓ End/tail
  - Middle

# Inserting an element into linked list n = 0

- Insert an element to the front:
  - Construct a node to be inserted, new\_node
  - Assign new\_node's next to NULL
  - Case 1:
    - Head is NULL (the list is empty)
    - Simply let head point to new\_node
  - Case 2:
    - Head is not NULL (the list is not empty)
    - new\_node's next points to the 1<sup>st</sup> node;
    - head point to new\_node

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## Inserting an element into linked list

- Insert an element to the end:
  - Construct a node to be inserted, new\_node
    - n-n->next = NUL
  - Case 1:
    - Head is NULL (the list is empty)
    - Simply let head point to new\_node
  - Case 2:
    - Head is not NULL (the list is not empty)
    - <u>Loop</u> to find the last element, last\_node
    - last\_node's next points to the new\_node;

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#### Inserting an element into linked list

- Insert an element to the middle:
  - Construct a node to be inserted, new\_node
     n\_n >next = ハレレレ
  - Case 1:
    - Head is NULL (the list is empty)
    - Simply let head point to new\_node
  - Case 2:
    - Head is not NULL (the list is not empty)
    - Loop to find the position to insert, after\_this\_node
    - new\_node's next points to the after\_this\_node's next
    - after\_this\_node's next points to the new\_node

- Opposite steps as inserting a new one
- Ex. Assuming the list is not empty, and we want to remove the node containing the value 8:



- Step 1:
  - Loop to find the node to be removed and the node before, i.e., current points to before\_node, node\_to\_remove points to the node to be removed



- Step 2:
  - Set current's next to node to remove's next



- Step 3:
  - free node\_to\_remove



## Missing topic: Command-line Arguments

- Arguments passed into main()
  - int main(int argc, char \*\*argv) OR
  - int main(int argc, char \*argv[])
- Allow you to take input(s) from the user before running your program
- argc: number of arguments
- argv: Array of c-style strings

## Example: ≤

• What is the value of argc if user entered this command to run the program?



• What does the 2-d array (**argv**) look like for the above command-line arguments?



## Lecture Topics:

- Dynamic Array (cont.)
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#### How to compare Data Structures?

- We have different data structures, how to compare them?
- We want a way to characterize runtime or memory usage that is completely platform-independent
  - i.e. does not depend on hardware, operating system, programming language, etc.

## **Complexity Analysis**

- Use Complexity Analysis to help make platform-independent comparisons of data structures
  - Also known as Big O

- To do this, we describe how a data structure's runtime or memory usage changes relative to a change in the input size (n)
  - Importantly, we want to describe how data structures behave in the limit, as n approaches
     (infinity)



- We use **Big O notation** to assess a data structure or algorithm's performance.
- Big O notation: a tool for characterizing a function in terms of its growth rate
  - Indicate an upper bound on the function's growth rate, known as growth order

## Big O



#### Common growth order functions



## Common growth order functions

- O(1) constant complexity
- O(log n) log-n complexity
- $O(\sqrt{n})$  root-n complexity
- O(n) linear complexity
- O(n log n) n-log-n complexity
- $O(n^2)$  quadratic complexity
- $O(n^3)$  cubic complexity
- $O(2^n)$  exponential complexity
- O(n!) factorial complexity