

# CS 261-020

# Data Structures

Lecture 7

Stack, Queue, Deque (cont.)

Encapsulation and Iterators

2/6/24, Tuesday



**Oregon State**  
University

# Odds and Ends

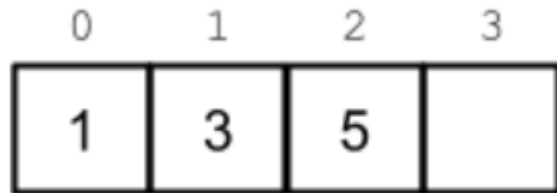
- Recitation 5 posted
- Assignment 2 due Sunday midnight
- Assignment 1 demo due Friday (2/9)
- Midterm:
  - Tuesday (2/13) during lecture time
  - Same classroom
  - Review on Thursday

# Lecture Topics:

- Stacks, Queues, and Deques
  - Linear ADTs
- Encapsulation and Iterators

# Implement Queue using Dynamic Array

- Using a dynamic array,
  - **Front** of the queue = **front** of the array
  - **Back** of the queue = **back** of the array
- Ex. A queue with 3 values (1 at the front, 5 at the back)



- ✓ **Enqueue** a new value → **insert** it at the **end** of the array
- What about dequeue?

# Implement Queue using Dynamic Array



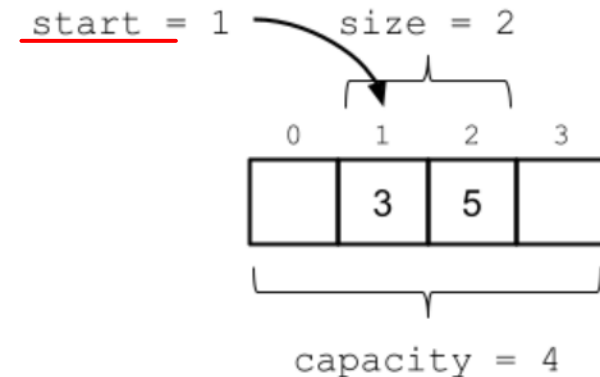
- Dequeue:

- Option 1: remove the front, and shift all the remaining to left

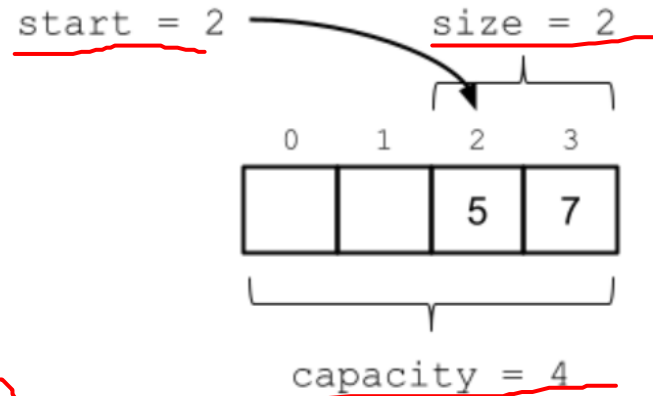
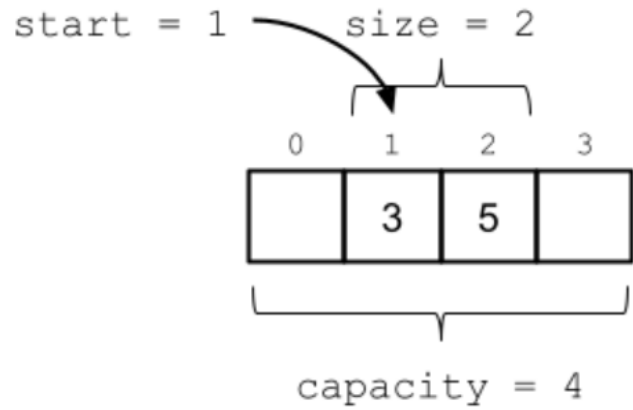
- Drawback:  $O(n)$  runtime complexity for each dequeue → **NOT GOOD!!!**

- Option 2: allow the front of the queue to “float” back into the middle of the array.

- Need to keep track of the **start** of the data

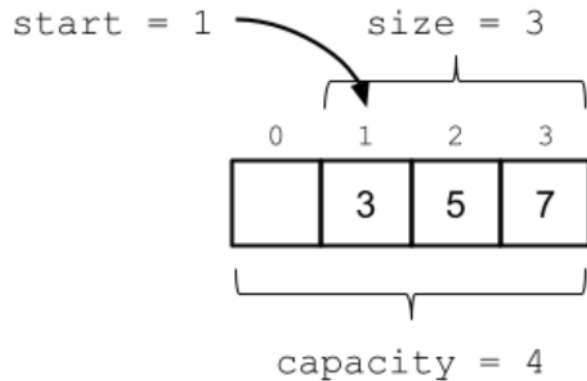


# Implement Queue using Dynamic Array

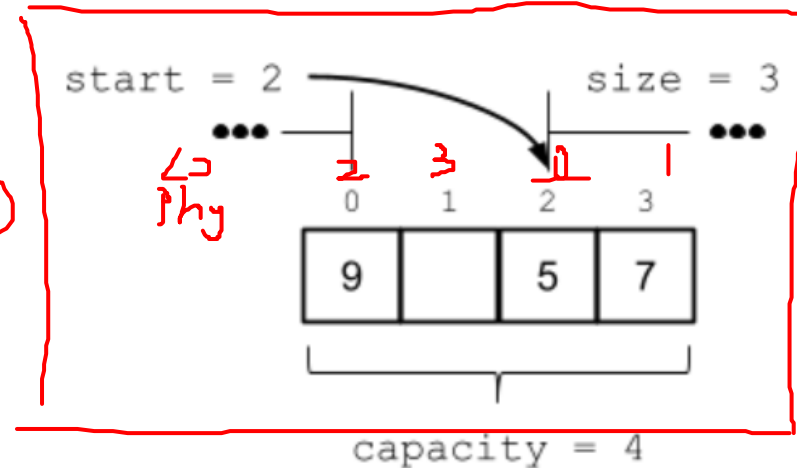


enqueue(7)

enqueue(9)



dequeue()



# Implement Queue using Dynamic Array

- An array that allows data to wrap around from the back to the front is known as a **circular buffer**
- Q: How do we know which index corresponds to the back of the queue?
  - By computing a mapping between the array's *logical indices* and its *physical indices*
- **Logical indices** – the indices relative to the **start of the data**
- **Physical indices** – the indices relative to the **start of the physical array**

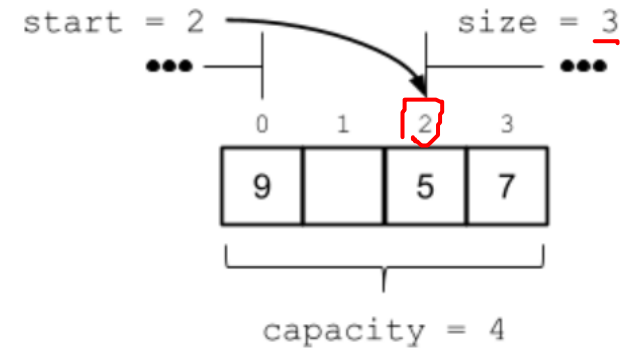
# Implement Queue using Dynamic Array

$engine(11)$   
 $phy = 2 + size$   
 $= 5$   
 $5 > Cap$   
 $phy = 5 - 4 = 1$

- Mapping formula:  $physical = \underline{start} + logical;$
- Since it is circular, add the following to check:

```

if (physical >= capacity) {
    physical -= capacity;
}
    
```



- OR:  $physical = (start + logical) \% capacity;$
- Index at which the next element will be inserted:
  - Previously:  $array[size]$  – when the data starts at physical index 0
  - Now:  $array[physical]$  – where  $physical = (start + size) \% capacity$



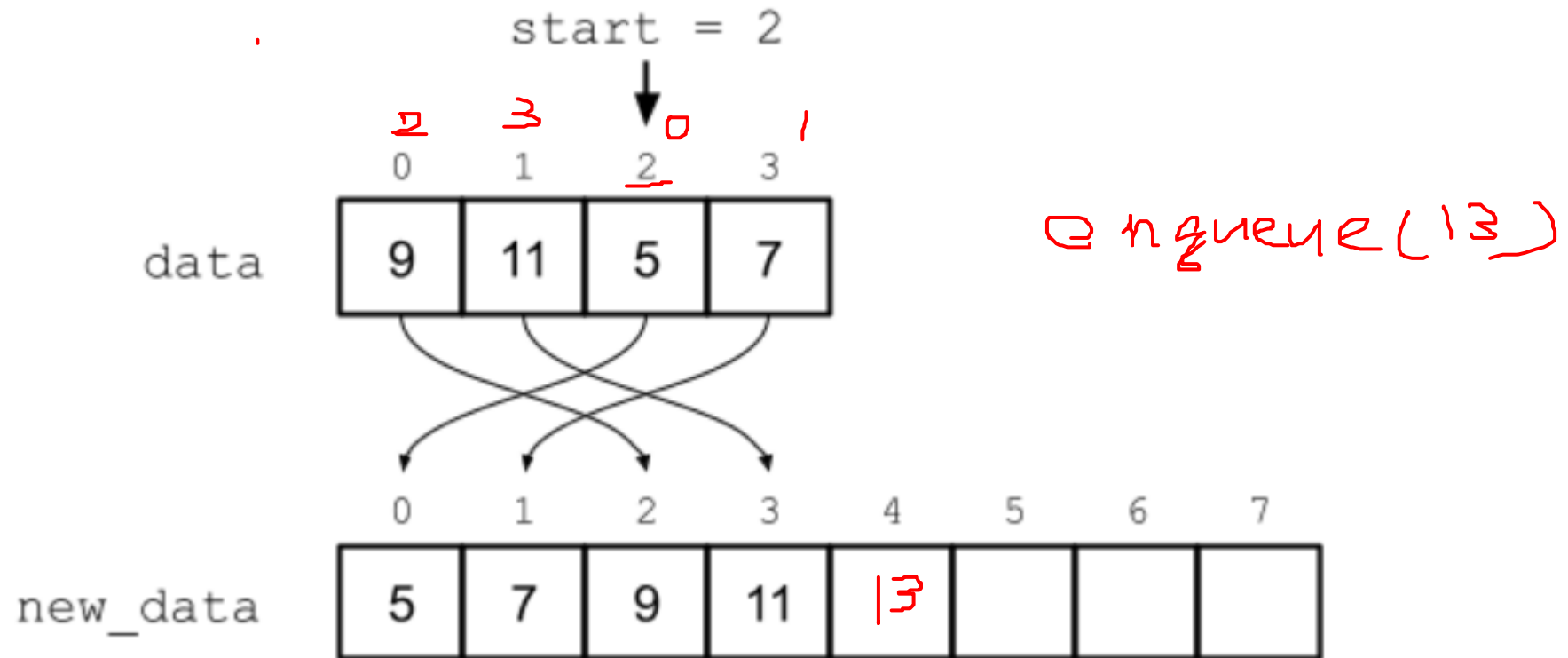
# Implement Queue using Dynamic Array

- Dynamic Array resizing for the queue implementation
- When do we need to resize?
  - size  $\geq$  capacity
- When resize, **reindex!**
  - Logical index 0  $\leftrightarrow$  Physical index 0
- How?
  - Loop through the **logical indices** from 0 to size - 1
  - Copy elements at each **logical index** in the old array to the equivalent **physical index** in the new array

# Implement Queue using Dynamic Array

- Visually, look like this:

`physical = (start + logical) % capacity;`



# Implement Queue using Dynamic Array

- Complexity:
  - Dequeue –  $O(1)$  for all best-case, worst-case, and average case
  - Enqueue
    - $O(1)$  for best-case and average case
    - $O(n)$  for worst-case, when resize is needed

# Dequeues



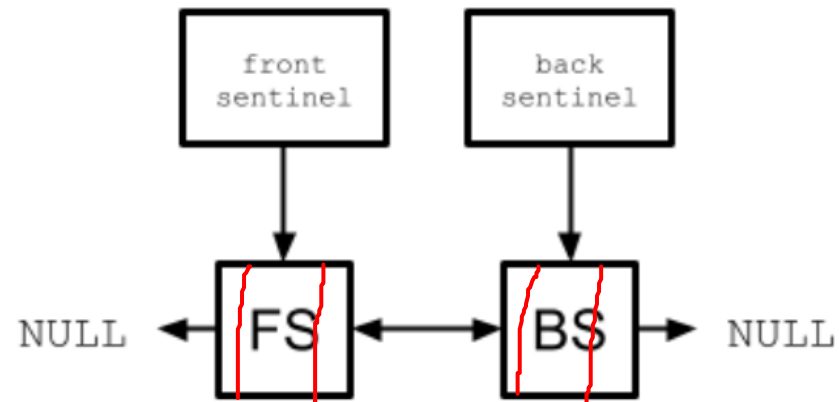
- A deque (double-ended queue) is a linear ADT that supports **insertion** and **removal** at **both ends**
- Examples: multi-processor job scheduling
- Four primary operations:
  - Add to front
  - Add to back
  - Remove from front
  - Remove from back

# \*Implement Deque using Dynamic Array

- Very similar to dynamic array-based queue implementation
  - Using circular buffer
- Not covered in this class
- FYI: <https://www.geeksforgeeks.org/implementation-deque-using-circular-array/>

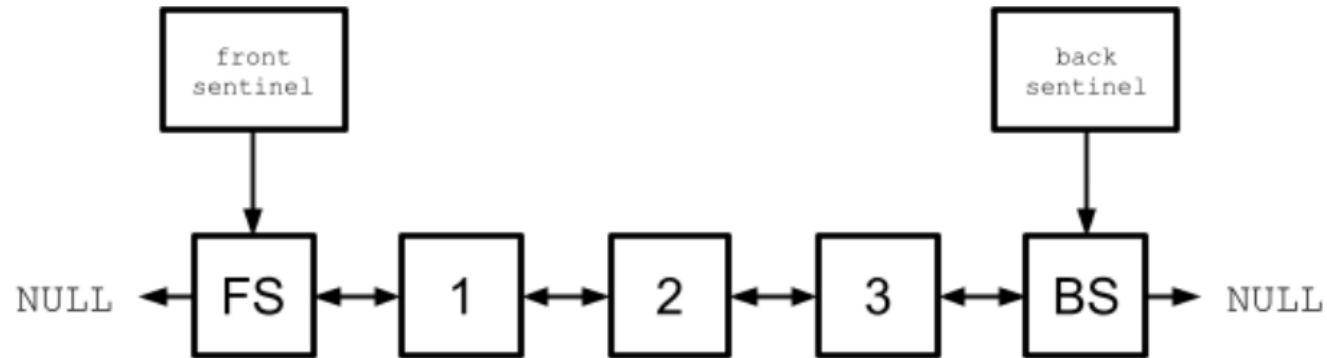
# Implement Deque using Linked List

- Since a deque supports removal from both front and back, we need to use a **doubly linked list**
  - Allows to remove from the back and find the new back
- Use **front and back sentinel** in the list
  - Sentinel: a special node that is **never removed** from the list (doesn't store a value)



# Implement Deque using Linked List

- Values are inserted into the list in nodes that live between the sentinels. For example:



- Add front: **insert** a new node **after** the front sentinel
- Add back: **insert** a new node **before** the back sentinel
- Remove front: **remove** the node **after** the front sentinel
- Remove back: **remove** the node **before** the back sentinel

# Implement Deque using Linked List

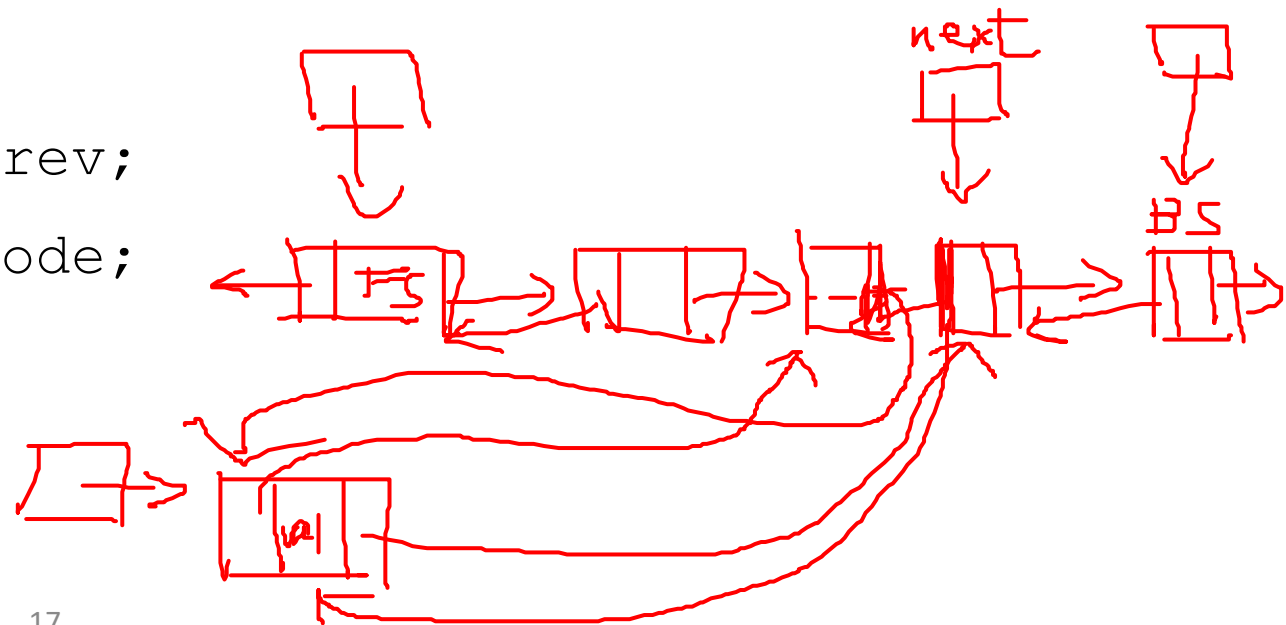
- Why do we use sentinels?
  - w/o sentinels, each operation would have to be implemented differently, i.e.:
    - Add to the front w/o sentinels → update the **head pointer** upon each insertion
    - Add to the back w/o sentinels → update the **tail pointer** upon each insertion
  - w/ sentinels, both insertions (add to front and add to back) can use the **exact same mechanics**
    - So can both of the removal operations



# Implement Deque using Linked List

- **add\_before()** – insert a new node with a given value before a specified node already in the list, i.e.:

```
void add_before(void* value, struct node* next) {  
    struct node* new_node = malloc(sizeof(struct node));  
    new_node->value = value;  
    new_node->prev = next->prev;  
    next->prev->next = new_node;  
    new_node->next = next;  
    next->prev = new_node;  
}
```



# Implement Deque using Linked List

- Since our list uses sentinels, then our **add\_to\_front()** becomes:

```
void add_to_front(void* value) {  
    add_before(value, front_sentinel->next);  
}
```

- Our **add\_to\_back()** becomes:

```
void add_to_back(void* value) {  
    add_before(value, back_sentinel);  
}
```

# Implement Deque using Linked List

- Similarly, assuming our list has a `remove_node()` function, then our `remove_front()` becomes:

```
void remove_front() {  
    remove_node(front_sentinel->next);  
}
```

- Our `remove_back()` becomes:

```
void remove_back() {  
    remove_node(back_sentinel->prev);  
}
```

- To check if the list is empty:

```
if (front_sentinel->next == back_sentinel)
```

# Implement Deque using Linked List

- Complexity:
  - Add to front –  $O(1)$
  - Add to back –  $O(1)$
  - Remove front –  $O(1)$
  - Remove back –  $O(1)$

\*For all best case, worst case, and average case

# Lecture Topics:

- Stacks, Queues, and Deques
  - Linear ADTs
- Encapsulation and Iterators

Have you seen this error before?

dereferencing a pointer of incomplete type



# Encapsulation

- Encapsulation – **hide the internal details of a data type** from the user of that data type, instead exposing only **a simplified interface** through which the user interacts with the data type
  - User – another developer who will be using the code we've written
- For example, linked list implementation has hidden **the details of the list implementation** behind a simplified interface.
  - Only the name of linked list data type was exposed to the user (i.e., `struct list`)
  - If the user tried to access internal fields (`list->head`) → error
    - “dereferencing a pointer of incomplete type”

# Why Encapsulation?

- Reduces the cognitive overhead to understand
- Cannot misuse (and possibly break) the data type
  - Cannot set `list->head` to `NULL` (could cause a memory leak)
- Easier to implement the data type
  - Avoid tedious error checking
- Potential challenges:
  - What if our user wants to **iterate through each element** in the collection within a loop?
    - Problem: cannot access the internals, i.e., for linked list, cannot access the `head`



# Iterator

- Iterator – a data type acts as **a companion to a collection** and provides a mechanism to **iterate through that collection**
  - Implemented to **have access to the internals** of the collection
- Each specific kind of collection will have its **own iterator data type**
- Two common functions:
  - **next ()** – returns the current value, and moves the iterator to the next element
  - **has\_next ()** – returns true or false to indicate whether or not there is another element afterwards

# To use an Iterator

- Assuming we have an iterator `iter` over a collection:

```
while (has_next(iter)) {  
    value = next(iter);  
    ... /* Do something with value. */  
}
```

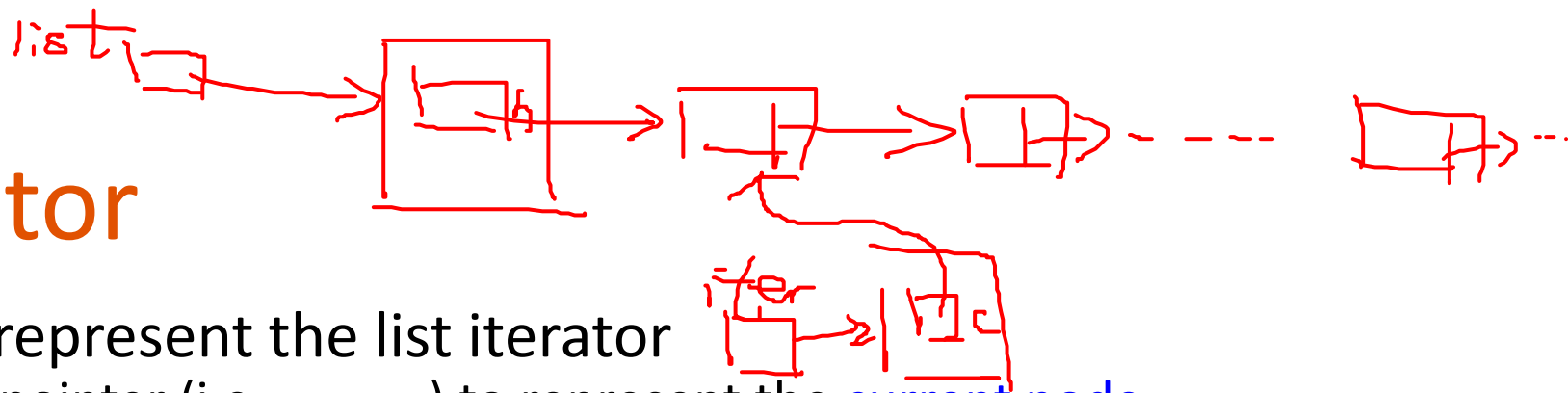
# Linked list Iterator

- Implement an iterator for a linked list:
  - In C: defined within the same file
  - In C++: using nested classes or friend
- Our linked list iterator must have access to the internals of the linked list:

```
struct node {  
    void* value;  
    struct node* next;  
};
```

```
struct list {  
    struct node* head;  
};
```

# Linked list Iterator



- 1. define a structure to represent the list iterator
  - How to iterate? Using a pointer (i.e., `curr`) to represent the **current node**
  - Initially points to the head, and moves to the next (i.e., `curr = curr -> next;`)

```
struct list_iterator {  
    struct node* curr;  
};
```

- 2. implement a function to create a new iterator and associate it with a list to iterate:

```
struct list_iterator* list_iterator_create(struct list* list) {  
    struct list_iterator* iter = malloc(sizeof(struct list_iterator));  
    iter->curr = list->head;  
    return iter;  
}
```

# Linked list Iterator

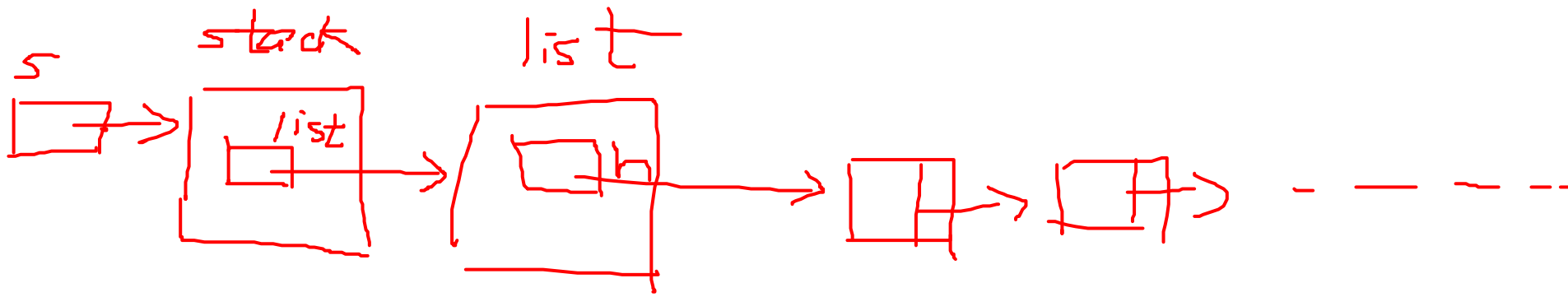
- 3. Implement `has_next()`

```
int has_next(struct list_iterator* iter) {  
    return iter->curr != NULL;  
}
```

- 4. Implement `next()`

```
void* next(struct list_iterator* iter) {  
    void* value = iter->curr->value;  
    iter->curr = iter->curr->next;  
    return value;  
}
```

- \*5. Polish (i.e., add error checking)



# Next Lecture

- Binary Search
- Midterm Review